

HYPERRULED SURFACES IN MINKOWSKI 4-SPACE*

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Abstract – In this paper, the time-like hyperruled surfaces in the Minkowski 4-space and their algebraic invariants are worked. Also some characteristic results are found about these algebraic invariants.

Keywords – Ruled surfaces, rulings, main curvature, scalar curvature, time-like vector

1. INTRODUCTION

The Minkowski space is the space R^4 with the Lorentzian inner product

$$g_0 = -dt^2 + dx^2 + dy^2 + dz^2$$

which is denoted by R_1^4 . The representation of g_0 in the matrix form with respect to the standard basis of R_1^4 is $\eta = \text{diag}(-1, 1, 1, 1)$. Suppose that R_1^4 is a 4-dimensional vector space over the field of real numbers. A symmetric bilinear form $\beta: R_1^4 \times R_1^4 \rightarrow R$ is called

- i) positive (resp. negative), definite if and only if $\vec{\omega} \neq \vec{0}$ implies $\beta\left(\vec{\omega}, \vec{\omega}\right) > 0$ (resp. $\beta\left(\vec{\omega}, \vec{\omega}\right) < 0$) for all $\vec{\omega}$ in R_1^4 ,
 - ii) non-degenerate if and only if $\beta\left(\vec{\omega}, \vec{z}\right) = 0$ for all \vec{z} in R_1^4 , implying that $\vec{\omega} = \vec{0}$, and
 - iii) indefinite if and only if there exists $\vec{\omega}$ and \vec{z} in R_1^4 such that $\beta\left(\vec{\omega}, \vec{\omega}\right) > 0$ and $\beta\left(\vec{z}, \vec{z}\right) < 0$,
- [1].

A non-degenerate, symmetric bilinear form β is called a *scalar product*. A scalar product may be positive definite, negative definite or indefinite.

For an indefinite scalar product β in R_1^4 , a nonzero vector $\vec{\omega}$ is said to be

- i) space-like if and only if $\beta\left(\vec{\omega}, \vec{\omega}\right) > 0$,
- ii) time-like if and only if $\beta\left(\vec{\omega}, \vec{\omega}\right) < 0$,
- iii) null if and only if $\beta\left(\vec{\omega}, \vec{\omega}\right) = 0$.

The vector $\vec{0}$ is taken to be *space-like*. The label space-like, time-like or null is called the *causal character* of a vector. A curve is called *time-like* (or *space-like*) *curve* if the tangent vector at every point of the curve is a time-like (or space-like) vector. A surface is called *time-like surface* if each

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tangential bundle of the surface is a time-like subspace of R_1^4 , [1]. A ruled surface is a surface swept out by a straight line ℓ moving along a curve α . Such a surface has a parametrization in the ruled form

$$\varphi(t, v) = \alpha(t) + ve_1(t),$$

where α is the *base curve* and e_1 is the *director vector* of ℓ . The various positions of the generating line ℓ are called the *rulings* of the surface. If the tangent plane is constant along a fixed ruling, then the ruled surface is called a *developable* or *cylindrical* surface. All other ruled surfaces are called *skew* surfaces [2].

2. TIME-LIKE RULED SURFACES

Let

$$\begin{aligned} \alpha : I &\rightarrow R_1^4 \\ t &\rightarrow \alpha(t) = (\alpha_1(t), \alpha_2(t), \alpha_3(t), \alpha_4(t)) \end{aligned} \quad (1)$$

be a differentiable time-like curve in the Minkowski space, where $0 \in I$.

A space-like straight line,

$$\begin{aligned} \ell : R &\rightarrow R_1^4 \\ v &\rightarrow \ell(v) = \alpha(t) + ve_1(t); \end{aligned} \quad (2)$$

where $e_1(t)$ is the director vector of ℓ at the point $\alpha(t)$ such that $e_1(t)$ and the tangent vector of α are linearly independent at every point of the curve α . Since ℓ is a space-like straight line $\langle e_1, e_1 \rangle = 1$, and \dot{e}_1 denotes the derivative of the vector field e_1 along the curve α , we have $\langle \dot{e}_1, e_1 \rangle = 0$.

When ℓ moves along α , it generates a ruled surface given by the chart $(I \times R, \varphi)$, where

$$\begin{aligned} \varphi : I \times R &\rightarrow R_1^4 \\ (t, v) &\rightarrow \varphi(t, v) = \alpha(t) + ve_1(t). \end{aligned} \quad (3)$$

This ruled surface will be denoted by M . Taking the derivatives of φ with respect to t and v , we have

$$\varphi_t = \dot{\alpha}(t) + v\dot{e}_1(t) \text{ and } \varphi_v = e_1(t).$$

Note that $\text{rank}[\varphi_t, \varphi_v] = \text{rank}[\dot{\alpha} + v\dot{e}_1, e_1] = 2$

So M is 2-manifold in the Minkowski space R_1^4 .

3. TIME-LIKE HYPERRULED SURFACES IN THE MINKOWSKI SPACE R_1^4

Throughout this section we assume that

$$1 \leq i, j \leq 2 \text{ and } 0 \leq m, n \leq 2.$$

Let M be a time-like ruled surface in R_1^4 , with a base curve α and the generating line ℓ . If we take the space-like plane $E_2(t)$ with spanning by the vectors $e_i(t)$, instead of the generating line ℓ ,

then M is a 3-manifold in R_1^4 . In this case M is called a *hyperruled surface* and can be (locally) represented by the chart (U, φ) , where $U = I \times R^2$ and

$$\begin{aligned} \varphi: I \times R^2 &\rightarrow R_1^4 \\ (t, v) &\rightarrow \varphi(t, v) = \alpha(t) + v^i e_i(t), \quad v = (v^1, v^2). \end{aligned} \quad (4)$$

Suppose that the base curve α is an orthogonal trajectory of the generating plane $E_2(t)$. If

$$\text{rank}[e_0, e_1, e_2, \dot{e}_1, \dot{e}_2] = 4 - k \quad (5)$$

Then

i) if $k = 0$ in (5), then M is called non-developable,

ii) if $k = 1$ in (5), then M is called developable,

where e_0 is the unit tangent vector field of the base curve α , which is a time-like curve, and \dot{e}_i is the derivative of the vector fields e_i along α .

We begin with some properties of a general pseudo-Riemann manifold M . Suppose that \bar{D} is the Levi-Civita connection on R_1^4 , while D is the Levi-Civita connection of M . Then, for any vector fields X, Y on M , we have the Gauss equation:

$$\bar{D}_X Y = D_X Y + V(X, Y) \quad (6)$$

where V is the second fundamental form of M .

If the ξ is the unit normal vector field on M , we have the Weingarten equation giving the tangential and normal components of $\bar{D}_X \xi$:

$$\bar{D}_X \xi = -A_\xi(X) + D_X^\perp \xi, \quad (7)$$

where A_ξ is determined at each point of a self-adjoint linear map on $\chi(M)$, and D^\perp is a metric connection in the normal bundle of M [3].

Let $X, Y \in \chi(M)$ and $\xi \in \chi(M^\perp)$. Then, by combining (6), (7) and the Minkowski inner product on R_1^4 , denoted by $\langle \cdot, \cdot \rangle$, yield that

$$\langle V(X, Y), \xi \rangle = \langle Y, A_\xi(X) \rangle. \quad (8)$$

Assume that $\{e_0, e_1, e_2\}$ is an orthonormal base field of the tangential bundle of M and ξ is the unit normal vector field of M . Then we have the following Weingarten equation

$$\bar{D}_{e_m} \xi = a_m^n e_n + b_m \xi, \quad (9)$$

where the Einstein summation is used. a_m^n 's are coefficients of the matrix A_ξ , and

$$a_m^n = \langle \bar{D}_{e_m} \xi, e_n \rangle = - \langle \xi, \bar{D}_{e_m} e_n \rangle.$$

Since the generating space $E_2(t)$ of M is a space-like subspace in R_1^4 , we have that $\langle e_i, e_j \rangle = \delta_{ij}$ and $\bar{D}_{e_i} e_j = 0$, which imply that $a_i^j = 0$ and

$$a_0^n = \langle \bar{D}_{e_0} \xi, e_n \rangle = - \langle \xi, \bar{D}_{e_0} e_n \rangle = - \langle \xi, \dot{e}_n \rangle = -a_n,$$

so we may write the matrix A_ξ as

$$A_{\xi} = \begin{bmatrix} a_0 & -a_1 & -a_2 \\ a_1 & 0 & 0 \\ a_2 & 0 & 0 \end{bmatrix}.$$

Lemma 3. 1. Consider the orthonormal base fields e_0, e_1, e_2 of M . Then the Riemannian curvature $\kappa_{\sigma}(e_i, e_0)$ in the two-dimensional direction σ of $\chi(M)$, spanned by the vector fields e_i and e_0 , is given by

$$\kappa_{\sigma}(e_i, e_0) = - \langle \bar{D}_{e_i} e_0, \bar{D}_{e_i} e_0 \rangle. \quad (10)$$

Proof: Suppose that R is the curvature tensor of M , then

$$\kappa_{\sigma}(e_i, e_0) = \langle e_i, R(e_i, e_0)e_0 \rangle.$$

But we see from the Gauss equation that

$$\langle e_i, R(e_i, e_0)e_0 \rangle = \langle V(e_i, e_i), V(e_0, e_0) \rangle - \langle V(e_i, e_0), V(e_i, e_0) \rangle$$

and we know that $V(e_i, e_i) = 0$. Moreover, we have

$$\langle \bar{D}_{e_i} e_0, e_j \rangle = \langle e_0, \bar{D}_{e_i} e_j \rangle = 0 \Rightarrow \bar{D}_{e_i} e_0 \perp e_j$$

and

$$\langle \bar{D}_{e_i} e_0, e_0 \rangle = \langle e_0, \bar{D}_{e_i} e_0 \rangle = 0 \Rightarrow \bar{D}_{e_i} e_0 \perp e_0.$$

This means that $\bar{D}_{e_i} e_0$ is a normal vector field or

$$\bar{D}_{e_i} e_0 = V(e_i, e_0) \quad (11)$$

which completes the proof.

4. THE ALGEBRAIC INVARIANTS OF THE HYPERRULED SURFACES IN THE SPACE R_1^4

Let M be a time-like hyperruled surface in the Minkowski 4-space R_1^4 . Then the space of tangent vector fields of M denoted by $\chi(M)$, is a time-like vector subspace of R_1^4 over the field of real numbers. Let A be linear operator on $\chi(M)$. A characteristic value of A is a scalar λ in R such that there exists a non-zero vector field X in $\chi(M)$, with $A(X) = \lambda X$, where X is called the *characteristic vector* of A corresponding to λ . The set of all X 's is called the *characteristic space* of A .

The function $f(\lambda) = \det(A - \lambda \epsilon)$ is called the characteristic polynomial of A , where $\epsilon = \text{diag}(-1, 1, 1, 1)$ is the matrix of the induced metric on $\chi(M)$. In order to find the roots of the characteristic polynomial we must solve the characteristic equation $\det(A - \lambda \epsilon) = 0$

$$\begin{vmatrix} a_0 + \lambda & -a_1 & -a_2 \\ a_1 & -\lambda & 0 \\ a_2 & 0 & -\lambda \end{vmatrix} = (a_0 + \lambda)\lambda^2 - a_1^2\lambda - a_2^2\lambda = 0$$

or

$$\lambda(\lambda^2 + a_0\lambda - a_1^2 - a_2^2) = 0.$$

This implies that

$$\lambda = 0 \text{ and } \lambda^2 + a_0\lambda - (a_1^2 + a_2^2) = 0$$

Since $\Delta = a_0^2 + 4(a_1^2 + a_2^2) > 0$, the solution of the characteristic equation are

$$\lambda_1 = 0, \lambda_2 = -\frac{1}{2}(a_0 + \sqrt{\Delta}) \text{ and } \lambda_3 = \frac{1}{2}(-a_0 + \sqrt{\Delta}).$$

Thus we may give the following result:

Result 4. 1. Let M be a time-like hyperruled surface in R_1^4 . If $\lambda_2 = \lambda_3$, then M is minimal and developable.

Proof: Let $\lambda_2 = \lambda_3$, then $\Delta = 0$, which implies that $a_0 = a_1 = a_2 = 0$.

Thus $a_0 = 0$ implies that $trA_{\xi} = 0$, and so M is minimal.

By lemma 1, $a_i = 0$ implies that $\kappa(e_i, e_0) = 0$ and so M is developable.

Let us find the characteristic vector corresponding to characteristic values $\lambda_1, \lambda_2, \lambda_3$ of the matrix A . The vector field X_1 corresponding to λ_1 is obtained by the solution of the equation

$$AX_1 = 0 \Leftrightarrow X_1(t) = \left(0, t, -\frac{a_1}{a_2}t \right).$$

Similarly, the vector fields X_2 and X_3 , corresponding to λ_2 and λ_3 , are obtained by the solutions of the equations

$$AX_2 = \lambda_2 X_2 \Leftrightarrow X_2(t) = \left(t, -\frac{a_1}{\lambda_2}t, -\frac{a_2}{\lambda_2}t \right)$$

and

$$AX_3 = \lambda_3 X_3 \Leftrightarrow X_3(t) = \left(t, -\frac{a_1}{\lambda_3}t, -\frac{a_2}{\lambda_3}t \right).$$

Since the vector fields $X_k(t)$, $k = 1, 2, 3$ have one arbitrary parameter, the dimension of the characteristic space is equal to 1. Therefore, we can choose an orthonormal base field $\phi = \{\bar{X}_1, \bar{X}_2, \bar{X}_3\}$ of $\chi(M)$ corresponding to characteristic values $\lambda_1, \lambda_2, \lambda_3$.

If we denote the matrix of the linear map A with respect to the orthogonal base ϕ by S , then we observe that

$$S = \begin{bmatrix} 0 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{bmatrix}.$$

S is called as the *Weingarten* (or *Shape*) operator of M with respect to the base ϕ .

Thus we can state the following results:

Result 4. 2. Let M be a time-like hyperruled surface in R_1^4 , and S be the shape operator of M . Then

i) The main curvature of M is $\|H\| = -\frac{a_0}{3}$.

ii) The Gauss curvature of M is $\kappa = 0$.

Definition 4. 1. Let M be a time-like hyperruled surface with curvature tensor R in R_1^4 . If $\{e_0, e_1, e_2\}$ is an orthonormal base field of $\chi(M)$, then the Ricci curvature tensor S is defined by

$$S: \chi(M) \times \chi(M) \rightarrow R$$

$$(X, Y) \rightarrow S(X, Y) = \sum_m \varepsilon_m \langle R(e_m, X)Y, e_m \rangle$$

where

$$\varepsilon_m = \begin{cases} -1, & m = 0 \\ 1, & m = 1, 2 \end{cases}$$

The scalar curvature of M is defined by

$$r = \sum_m S(e_m, e_m),$$

and the scalar normal curvature of M is defined by

$$r_n = \sum_{\sigma, \nu} M(A\xi_\sigma A\xi_\nu - A\xi_\nu A\xi_\sigma); \quad \sigma, \nu \in \{1, 2\}, [4].$$

Thus we can find the following results for the time-like hyperruled surfaces in the Minkowski 4-space R_1^4 :

Result 4. 3. Let M be a time-like hyperruled surface with a base curve α and the generating space $E_2(t)$ spanning by the vectors $e_i(t)$ in the Minkowski 4-space R_1^4 . Then the scalar curvature of M is

$$r = -2 \sum_i a_i^2,$$

where $a_i = \langle \xi, \dot{e}_i \rangle$ and $\xi \in \chi(M^\perp)$.

Proof: Let $\{e_0, e_1, e_2\}$ be an orthonormal base field of M . Then

$$r = \sum_m S(e_m, e_m) = S(e_0, e_0) + \sum_i S(e_i, e_i)$$

$$S(e_0, e_0) = \sum_m \langle R(e_m, e_0)e_0, e_m \rangle$$

$$= \sum_i \langle R(e_i, e_0)e_0, e_i \rangle$$

$$= \sum_i \kappa(e_i, e_0) = -\sum_i a_i^2$$

$$S(e_i, e_i) = \sum_m \langle R(e_m, e_i)e_i, e_m \rangle = \kappa_\sigma(e_i, e_0) = -a_i^2$$

which implies that $S(e_0, e_0) = -\sum S(e_i, e_i)$.

So we have $r = -2\sum S(e_i, e_i) = -2\sum a_i^2$.

Thus we derive the following results for a time-like hyperruled surface in R_1^4 :

- i) i) $r = 0$ if M is developable,
- ii) ii) $r = 0$ and M is minimal if M is hyperplane,
- iii) The scalar normal curvature of M is always zero.

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