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# An Iterative Approa
h for Estimation of Efficiency by Weighted Distance

R. Saneifard

Department of Mathemati
s, Oroumieh Bran
h, Islami Azad University, Oroumieh, Iran. Received 26 April 2010; revised 11 December 2010; accepted 26 December 2010.

#### **Abstract**

In group decision analysis, numerous approaches have been suggested in an attempt to solve the problem of aggregation of individual fuzzy opinion to form a group consensus as the basis of a group de
ision. If the inputs and outputs are fuzzy quantity, the de
ision making units can not be easily evaluated and ranked using the obtained efficiency scores. In this article, a kind of modified idea based on interactive method is introduced for ranking of decision making units with fuzzy data by weighted distance.

Keywords : Fuzzy number; Efficiency; Data envelopment analysis; Weighted distance.

# 1 Introduction

More and more, modeling techniques, control problems and operation research algorithms have been designed to fuzzy data since the concept of fuzzy number and arithmetic operations with these numbers was introduced and investigated first by Zadeh. Data envelopment analysis was suggested by Charnes, Cooper and Rhodes  $[2]$ , and built on the idea of Farrell [3] which is concerned with the estimation of technical efficiency and efficient frontiers. In some cases, we have to use imprecise input and output. To deal quantitatively with imprecision in decision progress, Bellman Zadeh [1] introduce the notion of fuzziness. Some researchers have proposed several fuzzy models to evaluate decision making units with fuzzy data and introduce a ranking approach with efficiency measure of the model [9]. In this paper, the researcher first introduces an approach with weighted distance for ranking of decision making units with crisp data. Second, this model is used for ranking of de
ision making units with fuzzy data.

This paper is organized as follows. In Section 2, the researcher recalls some fundamental

Email address: Saneifardiaurmia.a
.ir, Tel:+989149737077

results on fuzzy numbers. The proposed model is introduced in Section 3. An approach for ranking by using weighted distance is introduced in section 4. Interactive method is introdu
ed in Se
tion 5.

## 2 Preliminaries

The basic definition of a fuzzy number given in  $[5, 11, 12, 13, 14, 15]$  is as follows:

**Definition 2.1.** A fuzzy number is a mapping  $\mu : \Re \rightarrow [0, 1]$  with the following properties:

- 1.  $\mu$  is an upper semi-continuous function on  $\Re$ ,
- 2.  $\mu(x) = 0$  outside of some interval  $[a_1, b_2] \subset \Re,$
- 3. There are real numbers  $a_2, b_1$  such as  $a_1 \le a_2 \le b_1 \le b_2$  and
	- 3.1  $\mu(x)$  is a monotonic increasing function on  $[a_1, a_2]$ ,
	- 3.2  $\mu(x)$  is a monotonic decreasing function on  $[b_1, b_2]$ ,

3.3 
$$
\mu(x) = 1
$$
 for all x in  $[a_2, b_1]$ .

**Definition 2.2.** A fuzzy number is a fuzzy set A on the real line  $\Re$  such that

$$
\mu(x) = \begin{cases}\n f_A(x) & if \quad x \in [a_1, a_2], \\
 1 & if \quad x \in [a_2, a_3], \\
 g_A(x) & if \quad x \in [a_3, a_4], \\
 0 & otherwise.\n\end{cases}
$$
\n(2.1)

Such that  $f_A(.)$  is increasing function on  $[a_1, a_2]$  and  $g_A(.)$  is decreasing function on  $[a_3, a_4]$ .

The  $\alpha$ -cut of a fuzzy number A is defined as  $[A]^\alpha = \{x \mid u(x) > \alpha\}$ . Since  $\mu(.)$  is  $[A]^{\alpha} = [f_A^{-1}(\alpha), g_A^{-1}(\alpha)].$ 

**Definition 2.3.** A fuzzy number A in parametric form is a pair  $(A,\overline{A})$  of functions  $A(\alpha)$ and  $\overline{A}(\alpha)$  that  $0 \leq \alpha \leq 1$ , which satisfies the following requirements:

- 1.  $A(\alpha)$  is a bounded monotonic increasing left continuous function,
- 2.  $\overline{A}(\alpha)$  is a bounded monotonic decreasing left continuous function,
- 3.  $A\alpha$   $\leq \overline{A}(\alpha)$ ,  $0 \leq \alpha \leq 1$ .

**Definition 2.4.** The symmetric triangular fuzzy number  $A = (x_0, \sigma)$ , with defuzzifier  $x_0$ and fuzziness  $\sigma$  is a fuzzy set where the membership function is as

$$
\mu(x) = \begin{cases}\n\frac{1}{\sigma}(x - x_0 + \sigma) & x_0 - \sigma \leq x \leq x_0, \\
\frac{1}{\sigma}(x_0 - x + \beta) & x_0 \leq x \leq x_0 + \sigma, \\
0 & otherwise.\n\end{cases}
$$

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The parametric form of symmetric triangular fuzzy number is

$$
\underline{A}(\alpha) = x_0 - \sigma + \sigma \alpha \quad , \quad \overline{A}(\alpha) = x_0 + \sigma - \sigma \alpha.
$$

**Definition 2.5.** For fuzzy set  $A$  Support function is defined as follows:

$$
supp(A) = \overline{\{x|\mu(x) > 0\}},
$$

where  $\overline{\{x|\mu(x) > 0\}}$  is closure of set  $\{x|\mu(x) > 0\}$ .

 ${\bf Definition}$  2.6. [16], A function  $f:[0,1]\to [0,1]$  symmetric around  $\frac{1}{2},$  i.e.  $f(\frac{1}{2}-\alpha)=$  $f(\frac{1}{2} + \alpha)$  for all  $\alpha \in [0, \frac{1}{2}]$ , which reaches its minimum in  $\frac{1}{2}$ , is called the 01-symmetrical weighted function. The bi-symmetric function is also the bi-symmetric function is controlled function if

- $(1)$   $I(\pi) = 0$ ,
- $(2) f(0) = f(1) = 1$
- (3)  $\int_0^1 f(\alpha) d\alpha = \frac{1}{2}$ .

 ${\bf Definition~2.7.~}[14],$  For two arbitrary fuzzy numbers  $A$  and  $B$  with  $\alpha$ -cuts  $[f_A^{-1}(\alpha),g_A^{-1}(\alpha)]$ and  $[f_B](\alpha), g_B^-(\alpha)]$  respectively, the quantity

$$
d(A, B) = \left[\int_0^1 f(\alpha)(f_A^{-1}(\alpha) - f_B^{-1}(\alpha))^2 d\alpha + \int_0^1 f(\alpha)(g_A^{-1}(\alpha) - g_B^{-1}(\alpha))^2 d\alpha\right]^{\frac{1}{2}} \tag{2.2}
$$

is the weighted distan
e between A and B.

**Definition 2.8.** [4, 16], Let A is an arbitrary fuzzy number, the expected interval and expected value of a fuzzy number  $A$  are noted by  $EI(A)$  and  $EV(A)$  respectively, and considered as follows, (with  $f(\alpha) = \alpha$ ),

$$
EI(A) = [E_1^A, E_2^A] = [2 \int_0^1 \alpha f_A^{-1}(\alpha) d\alpha, 2 \int_0^1 \alpha g_A^{-1}(\alpha) d\alpha],
$$
  
\n
$$
EV(A) = \frac{E_1^A + E_2^A}{2} = \int_0^1 \alpha f_A^{-1}(\alpha) d\alpha + \int_0^1 \alpha g_A^{-1}(\alpha) d\alpha
$$
\n(2.3)

If  $A = (a_1, a_2, a_3, a_4)$  is a trapezoidal fuzzy number then:

$$
EI(A) = \left[\frac{a_1 + 2a_2}{3}, \frac{2a_3 + a_4}{3}\right],\tag{2.4}
$$

$$
EV(A) = \frac{1}{3}(a_1 + 2a_2 + 2a_3 + a_4). \tag{2.5}
$$

**Proposition 2.1.** If A and B are two fuzzy numbers and  $\lambda, \nu \in \mathbb{R}$  then:

$$
EI(\lambda A + \nu B) = \lambda EI(A) + \nu EI(B),
$$
  
\n
$$
EV(\lambda A + \nu B) = \lambda EV(A) + \nu EV(B),
$$
\n(2.6)

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The addition and scalar multiplication of fuzzy numbers are defined by the extension prin
iple and an be equivalently represented as follows. For arbitrary fuzzy numbers  $A = (\underline{A}, \overline{A})$  and  $B = (\underline{B}, \overline{B})$ , this article defines addition  $(A + B)$  and multiplication by scalar  $k > 0$  as

$$
(\underline{A+B})(\alpha) = \underline{A}(\alpha) + \underline{B}(\alpha) \quad , \quad (\overline{A+B})(\alpha) = \overline{A}(\alpha) + \overline{B}(\alpha), \tag{2.7}
$$

$$
(\underline{k}\underline{A})(\alpha) = k\underline{A}(\alpha) \quad , \quad (\overline{k}\overline{A})(\alpha) = k\overline{A}(\alpha). \tag{2.8}
$$

To emphasis the collection of all fuzzy numbers with addition and multiplication as defined by  $(2.2)$  and  $(2.3)$  denoted by  $F$ , which is a convex cone.

## 3 The proposed model

In this section, the researcher introduce ranking model based on weighted distance in data envelopment analysis. This article assumes that the  $DMU_p$  is extreme efficient [12, 6]. By omitting  $(X_p, Y_p)$  from  $T_c$  (PPS of CCR model), the researcher defines the production possibility set  $T_c$  as follows, [1]:

$$
T'_{c} = \{(X, Y) \mid X \ge \sum_{j=1, j \ne p}^{n} w_{j} X_{j}, Y \le \sum_{j=1, j \ne p}^{n} w_{j} Y_{j}, w_{j} \ge 0, j = 1, \cdots, n, j \ne p\}. (3.9)
$$

Where

$$
T_c = \{(X, Y) \mid X \ge \sum_{j=1}^n w_j X_j, Y \le \sum_{j=1, j \ne p}^n w_j Y_j, w_j \ge 0, j = 1, \cdots, n\}.
$$
 (3.10)

To obtain the ranking score of  $DMU_p$ , this article considers the following model:

$$
min \quad \Gamma_c^p(X, Y) = \sum_{i=1}^m f(\alpha)(x_i - x_{ip})^2 + \sum_{r=1}^s f(\alpha)(y_r - y_{rp})^2
$$
\n
$$
s.t \quad \sum_{j=1, j \neq p}^n w_j x_{ij} \le x_i, \qquad i = 1 \cdots, m,
$$
\n
$$
\sum_{j=1, j \neq p}^n w_j y_{rj} \ge y_r, \qquad i = 1 \cdots, s,
$$
\n
$$
x_i \ge 0, \qquad i = 1 \cdots, m,
$$
\n
$$
y_r \ge 0, \qquad r = 1 \cdots, s,
$$
\n
$$
w_j \ge 0, \qquad j = 1 \cdots, n, j \ne p.
$$
\n
$$
(3.11)
$$

Where  $X = (x_1, \ldots, x_n)$ ,  $Y = (y_1, \ldots, y_n)$  and  $\lambda = (\lambda_1, \ldots, \lambda_n)$  are the variables of the model (3.11) and  $\Gamma_c^p(X, Y)$  is the weighted distance  $(X_p, Y_p)$  from  $(X, Y)$  by weighted distance, also  $f(\alpha)$  is regular weighted function. Quadratic programming represents a special class of nonlinear programming in which the objective function is quadratic and the onstraints are linear. The KKT onditions of a quadrati programming problem redu
e to a linear omplementary problem. Thus the omplementary pivoting algorithm can be used for solving a quadratic programming problem.

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# 4 Comparison In Fuzzy DEA

In this section, the researcher supposes that inputs and outputs of DMUs are fuzzy numbers. Therefore,

$$
\tilde{T}'_c = \{ (X, Y) \mid X \ge \sum_{j=1, j \ne p}^n w_j \tilde{X}_j, Y \le \sum_{j=1, j \ne p}^n w_j \tilde{Y}_j, w_j \ge 0, j = 1, \cdots, n, j \ne p \} \quad (4.12)
$$

Weighted distance model with Eqs.  $(2.2)$  can be extended to the following model:

$$
min \quad \Gamma_c^p(X, Y) = \sum_{i=1}^m \left( \int_0^1 f(\alpha) (f_{x_i}^{-1}(\alpha) - f_{x_{ip}}^{-1}(\alpha))^2 d\alpha + \int_0^1 f(\alpha) (g_{x_i}^{-1}(\alpha) - g_{x_{ip}}^{-1}(\alpha))^2 d\alpha \right) + \sum_{r=1}^s \left( \int_0^1 f(\alpha) (f_{y_r}^{-1}(\alpha) - f_{y_{rp}}^{-1}(\alpha))^2 d\alpha + \int_0^1 f(\alpha) (g_{y_r}^{-1}(\alpha) - g_{y_{rp}}^{-1}(\alpha))^2 d\alpha \right) s.t \qquad (X, Y) \in \tilde{T}_c'.
$$
\n(4.13)

Where  $X = (x_1, \ldots, x_n)$ ,  $Y = (y_1, \ldots, y_n)$  and  $\lambda = (\lambda_1, \ldots, \lambda_n)$  are the variables of the model  $(4.13)$ , that all components of vectors X and Y for all DMUs are non-negative and each DMU has at least one strictly positive input and output.

For solving the model  $(4.13)$ , we have some following definitions:

**Definition 4.1.** [8], For any pair of fuzzy numbers A and B the degree in A is bigger than  $B$  has the following form:

$$
\mu_M(A, B) = \begin{cases}\n0 & if E_2^A - E_1^B < 0, \\
\frac{E_2^A - E_1^B}{E_2^A - E_1^A + E_2^B - E_1^B} & if 0 \in [E_1^A - E_2^B, E_2^A - E_1^B], \\
1 & if E_1^A - E_2^B > 0.\n\end{cases} \tag{4.14}
$$

Where  $[E_1^A, E_2^A]$  and  $[E_1^B, E_2^B]$  are the expected intervals of A and B. When  $\mu_M(A, B) = \frac{1}{2}$ ,  $$ we will say that A and B are different. When  $\mu_M(A, B) \geq \alpha$ , we will say that A is bigger than, or equal to B at least in degree  $\alpha$  and we will represent it by  $A \geq_{\alpha} B$ .

**Definition 4.2.** Given a production possibility  $(X,Y) \in T_c^{\prime}$ , we will say that it is product *in degree*  $\alpha$  *in*  $I_c$  *ij:* 

$$
\min \left\{ \begin{array}{c} \mu_M(x_i, \sum_{j=1, j \neq p}^n w_j \tilde{x}_{ij}) \ , \ \mu_M(\sum_{j=1, j \neq p}^n w_j \tilde{y}_{rj}, y_r) \\ \mu_M(x_i, \tilde{x}_{ip}) \ , \ \mu_M(\tilde{y}_{rp}, y_r) \\ i = 1, \dots, m \end{array} \right\} = \alpha. \tag{4.15}
$$

That is to say

$$
x_i \geq \alpha \sum_{j=1, j \neq p}^n w_j \tilde{x}_{ij} , \quad i = 1, \dots, m,
$$
  
\n
$$
y_r \leq \alpha \sum_{j=1, j \neq p}^n w_j \tilde{y}_{rj} , \quad r = 1, \dots, s.
$$
\n(4.16)

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There is:

$$
x_i \ge \sum_{j=1, j \ne p}^{n} w_j (\alpha E_2^{x_{ij}} + (1 - \alpha) E_1^{x_{ij}}) , \quad i = 1, ..., m,
$$
  

$$
y_r \le \sum_{j=1, j \ne p}^{n} w_j (\alpha E_1^{y_{rj}} + (1 - \alpha) E_2^{y_{rj}}) , \quad r = 1, ..., s.
$$
 (4.17)

(For more details see  $[12]$ ).

**Definition 4.3.** A production possibility  $(X_o, Y_o)^{\alpha} \in T_c'$  is an  $\alpha$ -acceptable optimal solution of model  $(4.13)$  if it is an optimal solution of the following model:

$$
min \quad \Gamma_c^p(X, Y)_{\alpha} = \sum_{i=1}^m \left( \int_0^1 f(\alpha) (f_{x_i}^{-1}(\alpha) - f_{x_i}^{-1}(\alpha))^2 d\alpha + \int_0^1 f(\alpha) (g_{x_i}^{-1}(\alpha) - g_{x_i}^{-1}(\alpha))^2 d\alpha \right) + \sum_{r=1}^s \left( \int_0^1 f(\alpha) (f_{y_r}^{-1}(\alpha) - f_{y_{rp}}^{-1}(\alpha))^2 d\alpha + \int_0^1 f(\alpha) (g_{y_r}^{-1}(\alpha) - g_{y_{rp}}^{-1}(\alpha))^2 d\alpha \right) s.t \qquad (X, Y) \in \tilde{T}_c'^{\alpha}.
$$
\n(4.18)

Where

$$
\tilde{T}_c'^{\alpha} = \{ (X, Y) \mid X \geq_{\alpha} \sum_{j=1, j \neq p}^{n} w_j \tilde{X}_j, Y \leq_{\alpha} \sum_{j=1, j \neq p}^{n} w_j \tilde{Y}_j, w_j \geq 0, j = 1, \cdots, n \} (4.19)
$$

Proposition 4.1. If  $\alpha_1 < \alpha_2$  then  $T_c'^{\alpha_2} \subseteq T_c'^{\alpha_1}$ .

We write model (4.18) as follows:

$$
min \quad \Gamma_c^p(X, Y)_{\alpha} = \sum_{i=1}^m \left( \int_0^1 f(\alpha) (f_{x_i}^{-1}(\alpha) - f_{x_{ip}}^{-1}(\alpha))^2 d\alpha + \int_0^1 f(\alpha) (g_{x_i}^{-1}(\alpha) - g_{x_{ip}}^{-1}(\alpha))^2 d\alpha \right) + \sum_{r=1}^s \left( \int_0^1 f(\alpha) (f_{y_r}^{-1}(\alpha) - f_{y_{rp}}^{-1}(\alpha))^2 d\alpha + \int_0^1 f(\alpha) (g_{y_r}^{-1}(\alpha) - g_{y_{rp}}^{-1}(\alpha))^2 d\alpha \right) s.t \qquad x_i \ge \sum_{j=1, j \ne p}^n w_j (\alpha E_2^{x_{ij}} + (1 - \alpha) E_1^{x_{ij}}) \quad i = 1, ..., m, y_r \le \sum_{j=1, j \ne p}^n w_j (\alpha E_1^{y_{rj}} + (1 - \alpha) E_2^{y_{rj}}) \quad r = 1, ..., s, y_r \ge 0 \qquad r = 1, ..., s, w_j \ge 0 \qquad j = 1, ..., n. \qquad (4.20)
$$

Model (4.20) is a crisp  $\alpha$ -parametric model. Therefore this article can solve it by the interactive method. Now this study is going to explain the interactive method.

#### Table 1

Fuzzy data of DMUs in fuzzy data in Example 4.1.





Table 2<br>The opti



## 4.1 Interactive Method

Regarding to proposition (4.1), to obtain the nearest  $(X, Y)$  of  $T_c$  implies a lesser degree of production possibility. Then the decision-maker runs in to two conflicting objectives: to find the nearest  $(X, Y)$  and to improve the degree of production possibility. Following Kaufman [11] the researcher considers 11 scales, which allow for different choice of decision-maker idea in  $(4.20)$  model.

1:  $\alpha = 0.0$  unacceptable solution 2:  $\alpha = 0.1$  Practically unacceptable solution 3:  $\alpha = 0.2$  Almost unacceptable solution 4:  $\alpha = 0.3$  Very unacceptable solution **5:**  $\alpha = 0.4$  Quite unacceptable solution 6:  $\alpha = 0.5$  Neither acceptable nor unacceptable solution 7:  $\alpha = 0.6$  Quite acceptable solution 8:  $\alpha = 0.7$  Very acceptable solution 9:  $\alpha = 0.8$  Almost acceptable solution 10:  $\alpha = 0.9$  Practically acceptable solution 11:  $\alpha = 1.0$  Completely acceptable solution

We choice the  $\alpha_0$  is the minimum acceptable degree with decision-maker idea. Then, this article solving the (4.20)  $\alpha$ -parametric model for each  $\alpha_k$  that  $k = 1, \ldots, (10 - 10\alpha_0)$ . We obtain the  $\alpha_k$ -acceptable optimal fuzzy value of objective function of original model  $(4.13)$  with  $\alpha_k$ -acceptable solution of model  $(4.20)$  in model  $(4.13)$ .

#### 4.2 Example

**Example 4.1.** We will consider a simple example was introduced in  $[10]$  with its data listed in Table 1. These DMUs are evaluated by proposed model in 4.13 with different  $\alpha_k$ . The  $\alpha$ -parametric model is as follows:

$$
min \quad \int_0^1 \alpha(x - 11 - \alpha) d\alpha + 2 \int_0^1 \alpha(y - 10) d\alpha + \int_0^1 \alpha(x - 14 + 2\alpha) d\alpha
$$
  
s.t 
$$
x \ge 30w_B + 40w_C + w_D(53.5 - 7.5\alpha)
$$
  

$$
y \le w_B(15 - 2.5\alpha) + 11w_C + w_D(20.5 - 7\alpha)
$$
  

$$
x \ge 0,
$$
  

$$
y \ge 0,
$$
  

$$
w_B, w_C, w_D \ge 0.
$$
  
(4.21)

The  $\alpha$ -parametric model for B, C and D can be showed similarly. The results is shown in Table 2.

## 5 Con
lusion

In the present arti
le a modied approa
h based on weighted distan
e is introdu
ed for ranking of decision making units with fuzzy data. The method is based on the interactive method.  $\alpha$ -acceptable optimal solution of proposed model for  $\alpha > \frac{1}{2}$  is an acceptable solution. For any decision making unit, the score of ranking is obtained by solving  $\alpha$ parametri model (4.20).

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