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NOTE ON EDGE DISTANCE-BALANCED GRAPHS

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ABSTRACT. Edge distance-balanced graphs are graphs in which for every edge e = uv the number of edges closer to vertex u than to vertex v is equal to the number of edges closer to v than to u. In this paper, we study this property under some graph operations.

1. Introduction

Let a and b be two adjacent vertices of the graph G, and e=ab the edge connecting them. For an edge e=ab of a graph G, let $n_a^G(e)$ be the number of vertices closer to a than to b. In other words, $n_a^G(e)=|\{u\in V(G)|d(u,a)< d(u,b)\}|$. In addition, let $n_0^G(e)$ be the number of vertices with equal distances to a and b, i. e., $n_0^G(ab)=|\{u\in V(G)|d(u,a)=d(u,b)\}|$.

A graph G is said to be distance-balanced, if $n_a^G(e) = n_b^G(e)$, for each edge $e = ab \in E(G)$, see [1, 5] for details. These graphs were, at least implicitly, first studied by Handa [4] who is considered distance-balanced partial cubes. The term itself, however, is due to Jerebič et al. [7] who is studied distance-balanced graphs in the framework of various kinds of graph products. Let G be a graph, $e = uv \in E(G)$, $m_u^G(e)$ denotes the number of edges lying closer to the vertex u than the vertex v, and $m_v^G(e)$ is defined analogously. Here is our key definition. We call a graph G to be edge distance-balanced, if $m_a^G(e) = m_b^G(e)$ holds for each edge $e = ab \in E(G)$. As examples of edge distance-balanced graphs, we mention the complete graph K_n on $n \ge 2$ vertices and the complete bipartite graph $K_{n,n}$ on 2n vertices.

Let G and H be two graphs. The corona product GoH is obtained by taking one copy of G and |V(G)| copies of H; and by joining each vertex of the i^{th} copy of H to the i^{th} vertex of G,

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 $i=1,2,\cdots,|V(G)|$, see [10, 13]. The Cartesian product $G\times H$ of the graphs G and H has the vertex set $V(G\times H)=V(G)\times V(H)$ and (a,x)(b,y) is an edge of $G\times H$ if a=b and $xy\in E(H)$, or $ab\in E(G)$ and x=y.

The cluster $G\{H\}$ is obtained by taking one copy of G and |V(G)| copies of a rooted graph H, and by identifying the root of the i^{th} copy of H with the i^{th} vertex of G, i=1,2,...,|V(G)| [13]. The lexicographic product G=G[H] of graphs G and H with disjoint vertex sets V(G) and V(H) and edge sets E(G) and E(H) is the graph with vertex set $V(G) \times V(H)$ and $u=(u_1,v_1)$ is adjacent with $v=(u_2,v_2)$ whenever $(u_1$ is adjacent to $u_2)$ or $(u_1=u_2$ and v_1 is adjacent to $v_2)$, see [6, p. 22]. Suppose G is a simple connected graph. Following Yan et al. [12], we define the graphs S(G) and R(G) as follows:

- (a) S(G) is the graph obtained by inserting an additional vertex in each edge of G. Equivalently, each edge of G is replaced by a path of length 2.
- (b) R(G) is obtained from G by adding a new vertex corresponding to each edge of G, then joining each new vertex to the end vertices of the corresponding edge.

A regular graph is a graph where each vertex has the same number of neighbors. A regular graph with vertices of degree k is called a k-regular graph or regular graph of degree k. A triangle-free graph is a graph containing no graph cycles of length three. Our other notations are standard and taken mainly form [2, 8, 9, 11].

2. Main Results

In this section we study the conditions under which the standard graph products produce an edge distance-balanced graph.

Theorem 2.1. Let G and H be edge and vertex distance-balanced graphs. Then $G \times H$ is edge distance-balanced graphs.

Proof. Consider the following partition of $E(G \times H)$:

$$A = \{(a, x)(b, y) \in E(G \times H) | ab \in E(G), x = y\}$$

$$B = \{(a, x)(b, y) \in E(G \times H) | a = b, xy \in E(H)\}.$$

We assume that G and H are edge and vertex distance-balanced graphs, and $e \in A$. Notice that

$$\begin{array}{lcl} m_{(a,x)}^{(G\times H)}(e) & = & m_a^G(ab)|V(H)| + n_a^G(ab)|E(H)|, \\ m_{(b,y)}^{(G\times H)}(e) & = & m_b^G(ab)|V(H)| + n_b^G(ab)|E(H)|. \end{array}$$

Since G is edge and vertex distance-balanced, thus we have $n_a^G(ab) = n_b^G(ab)$ and $m_a^G(ab) = m_b^G(ab)$. Therefore, in this case we have $m_{(a,x)}^{(G \times H)}(e) = m_{(b,y)}^{(G \times H)}(e)$. In a similar way we can see that, for every edge e of B, we have $m_{(a,x)}^{(G \times H)}(e) = m_{(b,y)}^{(G \times H)}(e)$. Then $G \times H$ is edge distance-balanced graphs. \square

A graph G is called nontrivial if |V(G)| > 1.

Theorem 2.2. The corona product of two arbitrary, nontrivial and connected graphs is not edge distance-balanced.

Proof. Let G and H be nontrivial connected graphs. Assume that $uv = e \in E(GoH)$ such that $u \in V(G)$ and $v \in V(H_i)$, where H_i , $1 \le i \le |V(G)|$ is the i^{th} copy of H. Thus,

$$m_u^{GoH}(e) = (|V(G)| - 1)|E(H)| + |E(G)| + |V(G)||V(H)| - 1$$

 $+ |\{f \in E(H)|d_H(v, f) \ge 2\}|$

and $m_v^{GoH}(e) = deg_H(v)$. Therefore, $m_u^{GoH}(e) \neq m_v^{GoH}(e)$ and so GoH is not edge distance-balanced.

Theorem 2.3. The cluster of two arbitrary, nontrivial and connected graphs is not edge distance-balanced.

Proof. Let G and H be nontrivial connected graphs. Assume that $e = uv \in E(G\{H\})$ such that u is the root of the i^{th} copy of H and $u \neq v \in V(H_i)$. Thus,

$$m_u^{G\{H\}}(e) = |E(H)|(|V(G)| - 1) + |E(G)| + m_u^H(e)$$

and $m_v^{G\{H\}}(e) = m_v^H(e)$. Therefore, $m_u^{G\{H\}}(e) \neq m_v^{G\{H\}}(e)$ and so $G\{H\}$ is not edge distance-balanced.

Theorem 2.4. Let G and H be connected graphs. Then G[H] is edge distance-balanced if G is nontrivial, edge and vertex distance-balanced and H is triangle-free and regular.

Proof. Suppose that G is nontrivial, edge and vertex distance-balanced and H is triangle-free and regular. Consider the following partition of E(G[H]).

$$A = \{(a, x)(b, y) \in E(G[H]) | ab \in E(G) \text{ and } x, y \in V(H) \},$$

$$B = \{(a, x)(b, y) \in E(G[H]) | a = b \in V(G), xy \in E(H) \}.$$

Let $e = (a, x)(b, y) \in A$. According to the definition of the lexicographic product, it is clear that

$$m_{(a,x)}^{G[H]}(e) - m_{(b,y)}^{G[H]}(e) = (m_a^G(ab) - m_b^G(ab))|V(H)|^2$$

$$+ (n_a^G(ab) - n_b^G(ab))|E(H)|$$

$$+ |\{f \in E(H) \mid d_H(y,f) \ge 2\}|$$

$$- |\{f \in E(H) \mid d_H(x,f) \ge 2\}|.$$

Since G is edge and vertex distance-balanced, then $m_a^G(ab) = m_b^G(ab)$ and $n_a^G(ab) = n_b^G(ab)$ and since H is triangle-free and regular one can see that $|\{f \in E(H) \mid d_H(y,f) \geq 2\}| = |\{f \in E(H) \mid d_H(x,f) \geq 2\}|$. It follows that $m_{(a,x)}^{G[H]}(e) = m_{(b,y)}^{G[H]}(e)$. We now assume that $e = (a,x)(b,y) \in B$. It follows from the edge structure of G[H] that $m_{(a,x)}^{G[H]}(e) = m_{(b,y)}^{G[H]}(e)$, if H is triangle-free and regular. Therefore, for each $e = (a,x)(b,y) \in E(G[H])$, we have $m_{(a,x)}^{G[H]}(e) = m_{(b,y)}^{G[H]}(e)$ and thus G[H] is edge distance-balanced.

Theorem 2.5. Let G be a nontrivial connected graph. Then R(G) is edge distance-balanced if and only if G is a path with |V(G)| = 2.

Proof. Let G be a path with |V(G)| = 2. Then it is clear that R(G) is edge distance-balanced. Conversely, we assume that R(G) is an edge distance-balanced graph, where G be a graph with |V(G)| > 2. Then, there is at least an edge uv = e of G such that u is the end vertex of e with $deg_G(u) > 1$ or v is the end vertex of e with $deg_G(v) > 1$. Without loss of generality, we my assume that u is the end vertex of e with $deg_G(u) > 1$. Also, we assume that x is a new vertex corresponding to edge e of G. Then, $m_x^{R(G)}(xu) = 1$ and $m_u^{R(G)}(xu) > 1$. Thus $m_x^{R(G)}(xu) \neq m_u^{R(G)}(xu)$. Therefore R(G), |V(G)| > 2, is not an edge distance-balanced graph and hence G is a path with |V(G)| = 2. \square

Theorem 2.6. Let G be a nontrivial connected graph with a pendant. Then S(G) is not edge distance-balanced.

Proof. Suppose x is a pendent vertex and u is the new vertex such that u and x are adjacent in S(G). Then $m_x^{S(G)}(ux) = 0$ and $m_u^{S(G)}(ux) \ge 1$, proving the result.

Suppose G and H are graphs with disjoint vertex sets. Following Doslic [3], for given vertices $y \in V(G)$ and $z \in V(H)$ a splice of G and H by vertices y and z, $(G \cdot H)(y; z)$, is defined by identifying the vertices y and z in the union of G and H. Similarly, a link of G and H by vertices yand z is defined as the graph $(G \sim H)(y; z)$ obtained by joining y and z by an edge in the union of these graphs.

Theorem 2.7. Suppose G and H are rooted graphs with respect to the rooted vertices of a and b, respectively. The graph $(G \cdot H)(a; b)$ is edge distance-balanced if and only if for each $e = uv \in E(G)$ and $f = xy \in E(H)$ the following conditions are satisfied:

(2.1)
$$m_{u}^{G}(e) - m_{v}^{G}(e) = \begin{cases} |E(H)| & \text{if } d(v, a) < d(u, a) \\ 0 & \text{if } d(v, a) = d(u, a) \end{cases},$$
(2.2)
$$m_{x}^{H}(f) - m_{y}^{H}(f) = \begin{cases} |E(G)| & \text{if } d(y, b) < d(x, b) \\ 0 & \text{if } d(y, b) = d(x, b) \end{cases}.$$

(2.2)
$$m_x^H(f) - m_y^H(f) = \begin{cases} |E(G)| & \text{if } d(y,b) < d(x,b) \\ 0 & \text{if } d(y,b) = d(x,b) \end{cases}.$$

Proof. In the graph $(G \cdot H)(a;b)$, we put r=a=b. We partition edges of $(G \cdot H)(a;b)$ into the following two subsets:

$$A = \{e = uv \in E(G.H) | d(v,r) < d(u,r)\},\$$

$$B = \{e = uv \in E(G.H) | d(v,r) = d(u,r)\}.$$

We first assume that $(G \cdot H)(a; b)$ is edge distance-balanced. Suppose e = uv is an arbitrary edge of G. Then $e \in A$ or $e \in B$ and not both. If $e \in A$ then by the hypothesis $m_u^{G \cdot H}(e) = m_v^{G \cdot H}(e)$. On the other hand by the definition of splice, $m_v^{G \cdot H}(e) = m_v^G(e) + |E(H)|$ and $m_u^{G \cdot H}(e) = m_u^G(e)$. Thus, $m_u^G(e) = m_v^G(e) + |E(H)|$ and so $m_u^G(e) - m_v^G(e) = |E(H)|$. Next we assume that $e \in B$. Again by the hypothesis $m_u^{G \cdot H}(e) = m_v^{G \cdot H}(e)$ and by definition of splice we have, $m_v^{G \cdot H}(e) = m_v^G(e)$ and $m_u^{G.H}(e) = m_u^G(e)$. This implies that $m_u^G(e) = m_v^G(e)$. Therefore, the equation (1) is satisfied. In a similar way we can see that, for every edge e of H the equation (2) is satisfied.

Conversely, suppose that Eqs. (1,2) are satisfied and $e = uv \in A$ is arbitrary. Then $e \in E(G)$ or $e \in E(H)$ and not both. If $e \in E(G)$ then $m_u^{G.H}(e) = m_u^G(e)$ and $m_v^{G.H}(e) = m_v^G(e) + |E(H)|$. This implies that $m_u^{G.H}(e) - m_v^{G.H}(e) = m_u^G(e) - (m_v^G(e) + |E(H)|)$. Since $m_u^G(e) - m_v^G(e) = |E(H)|$, $m_u^{G.H}(e) - m_v^{G.H}(e) = 0$, as desired. Suppose that $e \in E(H)$. Then $m_u^{G.H}(e) = m_u^H(e)$ and $m_v^{G.H}(e) = m_v^H(e) + |E(G)|$, so $m_u^{G.H}(e) - m_v^{G.H}(e) = m_u^H(e) - (m_v^H(e) + |E(G)|)$. But by the hypothesis, $m_u^H(e) - m_v^H(e) = |E(G)|$, so $m_u^{G.H}(e) - m_v^{G.H}(e) = 0$. We now assume that $e \in B$ is arbitrary. If $e \in E(G)$ then by $m_u^{G.H}(e) = m_u^G(e)$ and $m_v^{G.H}(e) = m_v^G(e)$ we have $m_u^{G.H}(e) - m_v^G(e) = 0$. If $e \in E(H)$ then by $m_u^{G.H}(e) = m_u^H(e)$ and $m_v^{G.H}(e) = m_v^H(e)$ we have $m_u^{G.H}(e) - m_v^{G.H}(e) = m_v^{G.H}(e)$. This completes the proof.

Corollary 2.8. Suppose G_1, G_2, \ldots, G_n are connected rooted graphs with root vertices r_1, \ldots, r_n , respectively. Then

$$(G_1 \cdot G_2 \cdot \cdots \cdot G_n)(r_1; r_2; \cdots ; r_n)$$

is edge distance-balanced if and only if for each $i, 1 \le i \le n$, and for each $e = uv \in E(G_i)$ the following system of equations are satisfied:

$$m_u^{G_i}(e) - m_v^{G_i}(e) = \begin{cases} \sum_{j=1, j \neq i}^n |E(G_j)| & \text{if } d(v, r_i) < d(u, r_i) \\ 0 & \text{if } d(v, r_i) = d(u, r_i) \end{cases}.$$

$$n.$$

Proof. Induct on n.

Theorem 2.9. Suppose G and H are rooted graphs with respect to the rooted vertices of a and b, respectively. The graph $(G \sim H)(a;b)$ is edge distance-balanced if and only if |E(G)| = |E(H)| and for each $e = uv \in E(G)$ and $f = xy \in E(H)$ the following conditions are satisfied:

$$m_u^G(e) - m_v^G(e) = \begin{cases} |E(H)| + 1 & \text{if } d(v, a) < d(u, a) \\ 0 & \text{if } d(v, a) = d(u, a) \end{cases},$$

$$m_x^H(f) - m_y^H(f) = \begin{cases} |E(G)| + 1 & \text{if } d(y, b) < d(x, b) \\ 0 & \text{if } d(y, b) = d(x, b) \end{cases}.$$

Proof. The proof is similar to Theorem 2.7 and so omitted.

Corollary 2.10. Suppose G_1, G_2, \ldots, G_n are connected rooted graphs with root vertices r_1, \ldots, r_n , respectively. Then $(G_1 \sim G_2 \sim \cdots \sim G_n)(r_1; r_2; \cdots; r_n)$ is edge distance-balanced if and only if for each $i, 1 \leq i \leq n$, $|E(G_i)| = |E(G_1)|$ and for each $e = uv \in E(G_i)$ the following system of equations are satisfied:

$$m_u^{G_i}(e) - m_v^{G_i}(e) = \begin{cases} \sum_{j=1, j \neq i}^n |E(G_j)| + \binom{n}{2} & \text{if } d(v, r_i) < d(u, r_i) \\ 0 & \text{if } d(v, r_i) = d(u, r_i) \end{cases}.$$

Proof. Induct on n.

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