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NOTE ON EDGE DISTANCE-BALANCED GRAPHS

M. TAVAKOLI, H. YOUSEFI-AZARI AND A. R. ASHRAFI *

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ABSTRACT. Edge distance-balanced graphs are graphs in which for every edge e = uv the number of edges closer to vertex u than to vertex v is equal to the number of edges closer to v than to u. In this paper, we study this property under some graph operations.

1. Introduction

Let a and b be two adjacent vertices of the graph G, and e = ab the edge connecting them. For an edge e = ab of a graph G, let $n_a^G(e)$ be the number of vertices closer to a than to b. In other words, $n_a^G(e) = |\{u \in V(G) | d(u, a) < d(u, b)\}|$. In addition, let $n_0^G(e)$ be the number of vertices with equal distances to a and b, i. e., $n_0^G(ab) = |\{u \in V(G) | d(u, a) = d(u, b)\}|$.

A graph G is said to be distance-balanced, if $n_a^G(e) = n_b^G(e)$, for each edge $e = ab \in E(G)$, see [1, 5] for details. These graphs were, at least implicitly, first studied by Handa [4] who is considered distance-balanced partial cubes. The term itself, however, is due to Jerebič et al. [7] who is studied distance-balanced graphs in the framework of various kinds of graph products. Let G be a graph, $e = uv \in E(G), m_u^G(e)$ denotes the number of edges lying closer to the vertex u than the vertex v, and $m_v^G(e)$ is defined analogously. Here is our key definition. We call a graph G to be edge distancebalanced, if $m_a^G(e) = m_b^G(e)$ holds for each edge $e = ab \in E(G)$. As examples of edge distance-balanced graphs, we mention the complete graph K_n on $n \ge 2$ vertices and the complete bipartite graph $K_{n,n}$ on 2n vertices.

Let G and H be two graphs. The corona product GoH is obtained by taking one copy of G and |V(G)| copies of H; and by joining each vertex of the i^{th} copy of H to the i^{th} vertex of G,

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^{*}Corresponding author.

 $i = 1, 2, \dots, |V(G)|$, see [10, 13]. The Cartesian product $G \times H$ of the graphs G and H has the vertex set $V(G \times H) = V(G) \times V(H)$ and (a, x)(b, y) is an edge of $G \times H$ if a = b and $xy \in E(H)$, or $ab \in E(G)$ and x = y.

The cluster $G\{H\}$ is obtained by taking one copy of G and |V(G)| copies of a rooted graph H, and by identifying the root of the i^{th} copy of H with the i^{th} vertex of G, i = 1, 2, ..., |V(G)| [13]. The lexicographic product G = G[H] of graphs G and H with disjoint vertex sets V(G) and V(H) and edge sets E(G) and E(H) is the graph with vertex set $V(G) \times V(H)$ and $u = (u_1, v_1)$ is adjacent with $v = (u_2, v_2)$ whenever $(u_1$ is adjacent to $u_2)$ or $(u_1 = u_2$ and v_1 is adjacent to $v_2)$, see [6, p. 22]. Suppose G is a simple connected graph. Following Yan et al. [12], we define the graphs S(G) and R(G) as follows:

(a) S(G) is the graph obtained by inserting an additional vertex in each edge of G. Equivalently, each edge of G is replaced by a path of length 2.

(b) R(G) is obtained from G by adding a new vertex corresponding to each edge of G, then joining each new vertex to the end vertices of the corresponding edge.

A regular graph is a graph where each vertex has the same number of neighbors. A regular graph with vertices of degree k is called a k-regular graph or regular graph of degree k. A triangle-free graph is a graph containing no graph cycles of length three. Our other notations are standard and taken mainly form [2, 8, 9, 11].

2. Main Results

In this section we study the conditions under which the standard graph products produce an edge distance-balanced graph.

Theorem 2.1. Let G and H be edge and vertex distance-balanced graphs. Then $G \times H$ is edge distance-balanced graphs.

Proof. Consider the following partition of $E(G \times H)$:

$$\begin{array}{lll} A &=& \{(a,x)(b,y) \in E(G \times H) | ab \in E(G), x = y\} \\ B &=& \{(a,x)(b,y) \in E(G \times H) | a = b, xy \in E(H)\}. \end{array}$$

We assume that G and H are edge and vertex distance-balanced graphs, and $e \in A$. Notice that

$$\begin{array}{lcl} m^{(G\times H)}_{(a,x)}(e) & = & m^G_a(ab)|V(H)| + n^G_a(ab)|E(H)|, \\ m^{(G\times H)}_{(b,y)}(e) & = & m^G_b(ab)|V(H)| + n^G_b(ab)|E(H)|. \end{array}$$

Since G is edge and vertex distance-balanced, thus we have $n_a^G(ab) = n_b^G(ab)$ and $m_a^G(ab) = m_b^G(ab)$. Therefore, in this case we have $m_{(a,x)}^{(G \times H)}(e) = m_{(b,y)}^{(G \times H)}(e)$. In a similar way we can see that, for every edge e of B, we have $m_{(a,x)}^{(G \times H)}(e) = m_{(b,y)}^{(G \times H)}(e)$. Then $G \times H$ is edge distance-balanced graphs. \Box

A graph G is called nontrivial if |V(G)| > 1.

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Theorem 2.2. The corona product of two arbitrary, nontrivial and connected graphs is not edge distance-balanced.

Proof. Let G and H be nontrivial connected graphs. Assume that $uv = e \in E(GoH)$ such that $u \in V(G)$ and $v \in V(H_i)$, where H_i , $1 \le i \le |V(G)|$ is the i^{th} copy of H. Thus,

$$m_u^{GoH}(e) = (|V(G)| - 1)|E(H)| + |E(G)| + |V(G)||V(H)| - 1$$
$$+ |\{f \in E(H)|d_H(v, f) \ge 2\}|$$

and $m_v^{GoH}(e) = deg_H(v)$. Therefore, $m_u^{GoH}(e) \neq m_v^{GoH}(e)$ and so GoH is not edge distance-balanced.

Theorem 2.3. The cluster of two arbitrary, nontrivial and connected graphs is not edge distancebalanced.

Proof. Let G and H be nontrivial connected graphs. Assume that $e = uv \in E(G\{H\})$ such that u is the root of the i^{th} copy of H and $u \neq v \in V(H_i)$. Thus,

$$m_u^{G\{H\}}(e) = |E(H)|(|V(G)| - 1) + |E(G)| + m_u^H(e)$$

and $m_v^{G\{H\}}(e) = m_v^H(e)$. Therefore, $m_u^{G\{H\}}(e) \neq m_v^{G\{H\}}(e)$ and so $G\{H\}$ is not edge distancebalanced.

Theorem 2.4. Let G and H be connected graphs. Then G[H] is edge distance-balanced if G is nontrivial, edge and vertex distance-balanced and H is triangle-free and regular.

Proof. Suppose that G is nontrivial, edge and vertex distance-balanced and H is triangle-free and regular. Consider the following partition of E(G[H]).

$$A = \{(a, x)(b, y) \in E(G[H]) | ab \in E(G) and x, y \in V(H) \},\$$

$$B = \{(a, x)(b, y) \in E(G[H]) | a = b \in V(G), xy \in E(H) \}.$$

Let $e = (a, x)(b, y) \in A$. According to the definition of the lexicographic product, it is clear that

$$\begin{split} m_{(a,x)}^{G[H]}(e) &= (m_a^G(ab) - m_b^G(ab))|V(H)|^2 \\ &+ (n_a^G(ab) - n_b^G(ab))|E(H)| \\ &+ |\{f \in E(H) \mid d_H(y,f) \ge 2\}| \\ &- |\{f \in E(H) \mid d_H(x,f) \ge 2\}|. \end{split}$$

Since G is edge and vertex distance-balanced, then $m_a^G(ab) = m_b^G(ab)$ and $n_a^G(ab) = n_b^G(ab)$ and since H is triangle-free and regular one can see that $|\{f \in E(H) \mid d_H(y, f) \ge 2\}| = |\{f \in E(H) \mid d_H(x, f) \ge 2\}|$. It follows that $m_{(a,x)}^{G[H]}(e) = m_{(b,y)}^{G[H]}(e)$. We now assume that $e = (a, x)(b, y) \in B$. It follows from the edge structure of G[H] that $m_{(a,x)}^{G[H]}(e) = m_{(b,y)}^{G[H]}(e)$, if H is triangle-free and regular. Therefore, for each $e = (a, x)(b, y) \in E(G[H])$, we have $m_{(a,x)}^{G[H]}(e) = m_{(b,y)}^{G[H]}(e)$ and thus G[H] is edge distance-balanced.

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Theorem 2.5. Let G be a nontrivial connected graph. Then R(G) is edge distance-balanced if and only if G is a path with |V(G)| = 2.

Proof. Let G be a path with |V(G)| = 2. Then it is clear that R(G) is edge distance-balanced. Conversely, we assume that R(G) is an edge distance-balanced graph, where G be a graph with |V(G)| > 2. Then, there is at least an edge uv = e of G such that u is the end vertex of e with $deg_G(u) > 1$ or v is the end vertex of e with $deg_G(v) > 1$. Without loss of generality, we my assume that u is the end vertex of e with $deg_G(u) > 1$. Also, we assume that x is a new vertex corresponding to edge e of G. Then, $m_x^{R(G)}(xu) = 1$ and $m_u^{R(G)}(xu) > 1$. Thus $m_x^{R(G)}(xu) \neq m_u^{R(G)}(xu)$. Therefore R(G), |V(G)| > 2, is not an edge distance-balanced graph and hence G is a path with |V(G)| = 2. \Box

Theorem 2.6. Let G be a nontrivial connected graph with a pendant. Then S(G) is not edge distance-balanced.

Proof. Suppose x is a pendent vertex and u is the new vertex such that u and x are adjacent in S(G). Then $m_x^{S(G)}(ux) = 0$ and $m_u^{S(G)}(ux) \ge 1$, proving the result.

Suppose G and H are graphs with disjoint vertex sets. Following Doslic [3], for given vertices $y \in V(G)$ and $z \in V(H)$ a splice of G and H by vertices y and z, $(G \cdot H)(y; z)$, is defined by identifying the vertices y and z in the union of G and H. Similarly, a link of G and H by vertices y and z is defined as the graph $(G \sim H)(y; z)$ obtained by joining y and z by an edge in the union of these graphs.

Theorem 2.7. Suppose G and H are rooted graphs with respect to the rooted vertices of a and b, respectively. The graph $(G \cdot H)(a; b)$ is edge distance-balanced if and only if for each $e = uv \in E(G)$ and $f = xy \in E(H)$ the following conditions are satisfied:

(2.1)
$$m_{u}^{G}(e) - m_{v}^{G}(e) = \begin{cases} |E(H)| & \text{if } d(v,a) < d(u,a) \\ 0 & \text{if } d(v,a) = d(u,a) \end{cases},$$
(2.2)
$$m_{x}^{H}(f) - m_{y}^{H}(f) = \begin{cases} |E(G)| & \text{if } d(y,b) < d(x,b) \\ 0 & \text{if } d(y,b) = d(x,b) \end{cases}.$$

Proof. In the graph $(G \cdot H)(a; b)$, we put r = a = b. We partition edges of $(G \cdot H)(a; b)$ into the following two subsets:

$$A = \{e = uv \in E(G.H) | d(v, r) < d(u, r)\},\$$

$$B = \{e = uv \in E(G.H) | d(v, r) = d(u, r)\}.$$

We first assume that $(G \cdot H)(a; b)$ is edge distance-balanced. Suppose e = uv is an arbitrary edge of G. Then $e \in A$ or $e \in B$ and not both. If $e \in A$ then by the hypothesis $m_u^{G \cdot H}(e) = m_v^{G \cdot H}(e)$. On the other hand by the definition of splice, $m_v^{G \cdot H}(e) = m_v^G(e) + |E(H)|$ and $m_u^{G \cdot H}(e) = m_u^G(e)$. Thus, $m_u^G(e) = m_v^G(e) + |E(H)|$ and so $m_u^G(e) - m_v^G(e) = |E(H)|$. Next we assume that $e \in B$. Again by the hypothesis $m_u^{G \cdot H}(e) = m_v^{G \cdot H}(e)$ and by definition of splice we have, $m_v^{G \cdot H}(e) = m_v^G(e)$ and Edge Distance-Balanced Graphs

 $m_u^{G.H}(e) = m_u^G(e)$. This implies that $m_u^G(e) = m_v^G(e)$. Therefore, the equation (1) is satisfied. In a similar way we can see that, for every edge e of H the equation (2) is satisfied.

Conversely, suppose that Eqs. (1,2) are satisfied and $e = uv \in A$ is arbitrary. Then $e \in E(G)$ or $e \in E(H)$ and not both. If $e \in E(G)$ then $m_u^{G.H}(e) = m_u^G(e)$ and $m_v^{G.H}(e) = m_v^G(e) + |E(H)|$. This implies that $m_u^{G.H}(e) - m_v^{G.H}(e) = m_u^G(e) - (m_v^G(e) + |E(H)|)$. Since $m_u^G(e) - m_v^G(e) = |E(H)|$, $m_u^{G.H}(e) - m_v^{G.H}(e) = 0$, as desired. Suppose that $e \in E(H)$. Then $m_u^{G.H}(e) = m_u^H(e)$ and $m_v^{G.H}(e) = m_v^H(e) + |E(G)|$, so $m_u^{G.H}(e) - m_v^{G.H}(e) = m_u^H(e) - (m_v^H(e) + |E(G)|)$. But by the hypothesis, $m_u^H(e) - m_v^H(e) = |E(G)|$, so $m_u^{G.H}(e) - m_v^{G.H}(e) = 0$. We now assume that $e \in B$ is arbitrary. If $e \in E(G)$ then by $m_u^{G.H}(e) = m_u^G(e)$ and $m_v^{G.H}(e) = m_v^G(e)$ we have $m_u^{G.H}(e) - m_v^G(e) = 0$. If $e \in E(H)$ then by $m_u^{G.H}(e) = m_u^H(e)$ and $m_v^{G.H}(e) = m_v^H(e)$ and $m_v^{G.H}(e) = m_v^H(e) - m_v^{G.H}(e) = m_v^G(e)$ and for every edge $e = uv \in E(G \cdot H)$, $m_u^{G.H}(e) = m_v^{G.H}(e) = m_v^{G.H}(e)$. This completes the proof.

Corollary 2.8. Suppose G_1, G_2, \ldots, G_n are connected rooted graphs with root vertices r_1, \ldots, r_n , respectively. Then

$$(G_1 \cdot G_2 \cdot \cdots \cdot G_n)(r_1; r_2; \cdots; r_n)$$

is edge distance-balanced if and only if for each $i, 1 \le i \le n$, and for each $e = uv \in E(G_i)$ the following system of equations are satisfied:

$$m_u^{G_i}(e) - m_v^{G_i}(e) = \begin{cases} \sum_{j=1, j \neq i}^n |E(G_j)| & \text{if } d(v, r_i) < d(u, r_i) \\ 0 & \text{if } d(v, r_i) = d(u, r_i) \end{cases}.$$

$$n.$$

Proof. Induct on *n*.

Theorem 2.9. Suppose G and H are rooted graphs with respect to the rooted vertices of a and b, respectively. The graph $(G \sim H)(a; b)$ is edge distance-balanced if and only if |E(G)| = |E(H)| and for each $e = uv \in E(G)$ and $f = xy \in E(H)$ the following conditions are satisfied:

$$\begin{split} m_u^G(e) - m_v^G(e) &= \begin{cases} |E(H)| + 1 & \text{if } d(v, a) < d(u, a) \\ 0 & \text{if } d(v, a) = d(u, a) \end{cases} \\ m_x^H(f) - m_y^H(f) &= \begin{cases} |E(G)| + 1 & \text{if } d(y, b) < d(x, b) \\ 0 & \text{if } d(y, b) = d(x, b) \end{cases}. \end{split}$$

Proof. The proof is similar to Theorem 2.7 and so omitted.

Corollary 2.10. Suppose G_1, G_2, \ldots, G_n are connected rooted graphs with root vertices r_1, \ldots, r_n , respectively. Then $(G_1 \sim G_2 \sim \cdots \sim G_n)(r_1; r_2; \cdots; r_n)$ is edge distance-balanced if and only if for each $i, 1 \leq i \leq n, |E(G_i)| = |E(G_1)|$ and for each $e = uv \in E(G_i)$ the following system of equations are satisfied:

$$m_u^{G_i}(e) - m_v^{G_i}(e) = \begin{cases} \sum_{j=1, j \neq i}^n |E(G_j)| + \binom{n}{2} & \text{if } d(v, r_i) < d(u, r_i) \\ 0 & \text{if } d(v, r_i) = d(u, r_i) \end{cases}.$$

Proof. Induct on *n*.

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M. Tavakoli

School of Mathematics, Statistics and Computer Science, University of Tehran, Tehran, I. R. Iran

H. Yousefi-Azari

School of Mathematics, Statistics and Computer Science, University of Tehran, Tehran, I. R. Iran

Ali Reza Ashrafi

Department of Mathematics, Faculty of Mathematics, Statistics and Computer Science, University of Kashan, Kashan 87317-51167, I. R. Iran

Email: ashrafi@kashanu.ac.ir