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Buckling Analysis of Polar Orthotropic Circular and Annular Plates of Uniform and Linearly Varying Thickness with Different Edge Conditions

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ABSTRACT

This paper investigates symmetrical buckling of orthotropic circular and annular plates of continuous variable thickness. Uniform compression loading is applied at the plate outer boundary. Thickness varies linearly along radial direction. Inner edge is free, while outer edge has different boundary conditions: clamped, simply and elastically restraint against rotation. The optimized Ritz method is applied for buckling analysis. In this method, a polynomial function that is based on static deformation of orthotropic circular plates in bending is used. Also, by employing an exponential parameter in deformation function, eigenvalue is minimized in respect to this parameter. The advantage of this procedure is simplicity, in comparison with other methods, while whole algorithm for solution can be coded for computer programming. The effects of variation of radius, thickness, different boundary conditions, ratio of radial Young modulus to circumferential one, and ratio of outer radius to inner one in annular plates on buckling load factor are investigated. The obtained results show that in plate with identical thickness, increasing of outer radius decreases the buckling load factor. Moreover, increase of thickness of the plates results in increase of buckling load factor.

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Keywords: Buckling; Orthotropic Plates; Circular and annular plates; Different edge conditions

1 INTRODUCTION

RTHOTROPIC circular and annular plates are always used by mechanical, civil, aerospace and structural engineers and designers. Some applications of these systems are pressure vessel valve, reinforced circular plates by radial and circumference supporter, composite plates, cylinder head cover, bulkhead plates in submarines, separated plates in aircraft, optical lenses, and acoustic transducers in rockets. Woinosky [1], for the first time, studied the problem of elastic stability of orthotropic circular plates. He introduced numeric results by using Bessel function for buckling of plates. Menk et al. [2] studied on variation of thickness on buckling of orthotropic rectangular plate. Laura et al. [3] found critical load of buckling for isotropic annular plate with constant thickness by optimized Rayleigh-Ritz method. Imposed boundary condition of plate for either inner edge or outer edge was under different supports. Cianco [4] studied on buckling of circular and annular isotropic plate with variable thickness that was used as a part of submarine. This plate was considered with free support on inner edge and clamped support and resistant of rotation for outer edge. The thickness of plate is exponential function of its radius. He analyzed the plate by optimized Rayleigh-Ritz method. Bremec et al. [5] also introduced one optimized rate of variation of thickness for buckling of isotropic plates which both in inner edge and outer edge was under constant O

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radial load and thickness was varied in radial direction. Buckling function was in linear fashion and solved by numeric method under simply and clamped support. Gutierrez et al. [6] considered buckling and vibration of the isotropic plate with variable thickness on elastic support using Rayleigh-Ritz method, and obtained acceptable results. Liang et al. [7] found natural frequencies of one orthotropic circular and annular plate with variable thickness using Rayleigh-Ritz method that agreed with the result of finite element method.

In this paper, buckling of orthotropic circular and annular plates with linear variation of thickness under constant compressive radial loading is studied. The boundary condition of annular plates are F-C plates (free inner, and clamped outer edge) or clamped circular solid ones, F-S plates (free inner, simply outer edge) or simply supported solid circular ones, and annular plates with free inner support and resistant elastic against rotation outer edge. Circular plates contain plates with clamped, simply and elastic resistant against rotation boundary condition. Solving buckling differential equation of orthotropic circular or annular plate with variable thickness is impossible by analytical method and it should be solved using numerical or energy method. For this reason, optimized Rayleigh-Ritz method is used. The results of this method is more precisely than Rayleigh-Ritz method. For optimization of Rayleigh-Ritz method, one exponential parameter in approximate function is considered. Eigenvalues (buckling load factor) that is obtained, are minimized according to this exponential parameter. Furthermore, the comparison between results of this method and the results of ANSYS commercial finite element package is done. The effects of thickness variation, boundary conditions, Young module ratio in radius and circumference axis, variation of ratio of inner radius to outer one on buckling load factor are considered.

2 THEORY

2.1 Basic f formulation of the problem

The formulation of the problem is derived under the following assumptions:

- 1. The plate is in the state of plane stress.
- 2. The stress-strain relationship follows orthotropic material.
- 3. The plate is thin. Therefore, the Kirchhoff assumptions are incorporated.
- 4. The thickness is varied in the direction of radius of the plate.

Consider a circular annular plate with variable thickness $h(r)$, a , b inner and outer radius, respectively as shown in Fig. 1. For buckling analysis, the in-plane displacement u and v may be neglected and only out-of-plane deformation w is considered. The governing energy functional can be given by:

$$
J = U + V \tag{1}
$$

where U is the stored strain energy per unit volume that in the polar coordinate system for plane stress is given as follows [8]:

$$
U = \frac{1}{2} \iiint_{v} (\sigma_r \varepsilon_r + \sigma_\theta \varepsilon_\theta + \tau_{r\theta} \gamma_{r\theta}) \, r \, dr \, d\theta \, dz \tag{2}
$$

The work done by in-plane radial force is given as:

$$
V = \frac{1}{2} \iint_{A} \left[N_r \left(\frac{\partial w}{\partial r} \right)^2 + N_\theta \left(\frac{\partial w}{\partial \theta} \right)^2 \right] r \, dr \, d\theta \tag{3}
$$

Fig g. 1 Schematic view of annular plate with variable thickness (centrally thicker circular plate).

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In the present study, the axial radial symmetry is assumed. Therefore, plate is independent of azimuthal variable:

$$
V = \pi \int_{b}^{a} N_r \left(\frac{\partial w}{\partial r}\right)^2 r \, dr \tag{4}
$$

For orthotropic annular plate, *V* is derived as follows [9]

$$
V = \pi \int_{b}^{a} \frac{-N_0}{h_a} \times \frac{a^{\beta+1}}{a^{2\beta} - b^{2\beta}} \left[r^{\beta-1} - \frac{b^{2\beta}}{r^{\beta+1}} \right] \left(\frac{\partial w}{\partial r} \right)^2 r \, dr \tag{5}
$$

Also, using the stress-strain relation for orthotropic material, substituting into Eq. (1), one may obtain:

$$
U = \frac{1}{2} \iiint_{v} \frac{z^2}{1 - v_r v_\theta} \left[E_r \left(\frac{d^2 w}{dr^2} \right)^2 + 2E_r v_\theta \left(\frac{d^2 w}{dr^2} \right) \left(\frac{dw}{dr} \right) + E_\theta \left(\frac{dw}{r dr} \right)^2 \right] r \, dr \, d\theta \, dz \tag{6}
$$

As shown in Fig 1 the thickness of plate is continuously varying *h*(*r*), with integrating along the thickness, the stored strain energy can be expressed by the following equation:

$$
U = \pi \int_{a}^{b} D_r(r) \left[\left(\frac{d^2 w}{dr^2} \right)^2 + 2 \nu_\theta \left(\frac{d^2 w}{dr^2} \right) \left(\frac{dw}{r dr} \right) + \beta^2 \left(\frac{dw}{r dr} \right)^2 \right] r \, dr \tag{7}
$$

where

$$
D_r(r) = \frac{E_r h^3(r)}{12(1 - \nu_r \nu_\theta)}, \qquad \frac{E_\theta}{E_r} = \frac{D_\theta(r)}{D_r(r)} = \beta^2
$$
\n(8)

In above equation, $D_r(r)$ and $D_\theta(r)$ denote circumferential and radial bending stiffness of the plate, respectively. In this study, annular and solid circular plates with continuously varying thickness are considered. The variation of thickness along the radius direction can be expressed as follows:

$$
h(r) = h_o \left(1 + \gamma \left(\frac{r}{a} \right)^n \right) \tag{9}
$$

where h_0 and *a* represent the thickness in the centre (inner radius for annular plate) and the outer radius of plate, respectively. In order to consider the influence of non uniform thickness on buckling load factor, two values are assigned for the parameter *n*, $n=0$, 1 for uniform and linearly varying thickness, respectively. γ is non-dimensional geometric parameter that may be positive (centrally thinner circular plate) or negative (centrally thicker circular plate) and is defined as follows:

For circular solid plates:

$$
\gamma = \frac{h_a}{h_o} - 1\tag{10}
$$

For circular annular plates:

$$
\gamma = \frac{h_b - h_o}{h_o(r_b)^n} \tag{11}
$$

In above equation, r_b is the ratio of inner radius to the outer one $(=b/a)$. In the sake of convenience, the variables in Eqs. (7) and (15) are transformed to dimensionless one, so the total potential energy functional is as follows:

$$
\frac{a^2}{\pi D_0} J(W) = \int_{r_b}^1 \left\{ g(R) \left[\left(\frac{d^2 W}{dR^2} \right)^2 + 2 \nu_\theta \left(\frac{d^2 W}{dR^2} \right) \left(\frac{dW}{R dR} \right) + \beta^2 \left(\frac{dW}{R dR} \right)^2 \right] - \frac{\lambda}{1 - r_b^{2\beta}} \left[R^{\beta - 1} - \frac{r_b^{2\beta}}{R^{\beta + 1}} \right] \left(\frac{dW}{dR} \right)^2 \right\} R \, dR \tag{12}
$$

that,

$$
g(R) = (1 + \gamma R)^3, \qquad D_0 = \frac{E_r h_o^3}{12(1 - \nu_r \nu_\theta)}, \qquad R = \frac{r}{a}
$$
\n(13)

where λ is the buckling load factor that is related to buckling load as follows:

$$
\lambda = \frac{N_0 a^2}{D_0} \tag{14}
$$

2.2 Optimized Ritz method

Considering the fact that Rayleigh-Ritz method is an upper bound method, the determined eigenvalue is more than real one. Therefore, if one can optimize it somehow, the results will be closer to real one. In general, the function which introduces the unknown quantity, is a linear combination of shape modes ϕ_n , as follows:

$$
f(x) = \sum_{n=1}^{N} c_n \varphi_n(x) \tag{15}
$$

where c_n is the unknown constants. According to the idea of optimization, by performing the Optimized Rayleigh-Ritz method, it is quite convenient to approximate $f(x)$ by means of a summation:

$$
f(x) = \sum_{n=1}^{N} c_n \varphi_n(x, k) \tag{16}
$$

Note that k in above equation is the exponential optimization parameter. Regarding to the Eq. (16), out-plane displacement *W*(*R*) is given as follows:

$$
W(R) = \sum_{i=1}^{N} c_i w_i(R, k)
$$
\n(17)

By minimizing potential energy functional in Rayleigh-Ritz method:

$$
\frac{\partial J}{\partial c_i} = 0, \qquad i = 1, ..., N \tag{18}
$$

Total number of *N* linear homogenous algebraic equations are generated that the unknowns are constants *cn*. It forms the eigenvalue problem that the eigenvlaues are the values of buckling load parameter. The non-trivial condition leads to a transcendental equation in whose lowest root is the desired buckling load factor [4]. Since $\partial \lambda / \partial k = 0$, by requiring, one is able to optimize the fundamental eigenvalue.

2.3 Buckling of annular plate

Regarding to the Eq. (17), $w_i(R, k)$ is defined as follows [9]

$$
w_i(R) = (a_i R^k + b_i R^{1+\beta} + 1) R^{i-1}
$$
\n(19)

Unknown constants a_i and b_i are determined by applying boundary conditions.

2.3.1 Clamped outer edge (F-C) plate

For a clamped outer edge, in $r=a$ or $R=1$, the governing boundary conditions are:

$$
\begin{cases} w_i(1) = 0\\ \frac{\mathrm{d}w_i}{\mathrm{d}R}(1) = 0 \end{cases} \tag{20}
$$

By substitution Eq. (19) into eq. (20), the a_i and b_i values are determined as follows:

$$
a_i = \frac{-1 - \beta}{1 + \beta - k}, \qquad b_i = \frac{k}{1 + \beta - k}
$$
 (21)

2.3.2 Simply supported outer edge (S-F) plate

For a simply supported outer edge, the out-plane displacement must satisfy the following conditions:

$$
\begin{cases} w_i(1) = 0 \\ \frac{d^2 w_i}{dR^2}(1) + v_\theta \frac{dw_i}{dR}(1) = 0 \end{cases}
$$
 (22)

Considering the boundary condition in outer edge, the a_i and b_i values are determined:

$$
a_i = \frac{(1+\beta)(-2+2i+\beta+\nu_\theta)}{(-1-\beta+k)(-2+2i+k+\beta+\nu_\theta)}
$$

\n
$$
b_i = -\frac{k(-3+2i+k+\nu_\theta)}{(-1-\beta+k)(-2+2i+k+\beta+\nu_\theta)}
$$
\n(23)

2.3.3 Elastically restrained against rotation

For the case of elastically restrained against rotation:

$$
\begin{cases} w_i(1) = 0 \\ \phi \frac{dw_i}{dR}(1) = -g(R) \left[\frac{d^2 w_i}{dR^2}(1) + v_\theta \frac{dw_i}{dR}(1) \right] \end{cases}
$$
 (24)

where a_i and b_i values are determined as follows:

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$$
a_i = -\frac{Q_i - L_i}{S_i - L_i}, \qquad b_i = -\frac{S_i - Q_i}{S_i - L_i}
$$
\n(25)

In above equation, S_i , Q_i , and L_i are defined as follows:

$$
S_i = (k + i - 1)[1 + g(R) \varphi(-2 + i + k + \upsilon_{\theta})]
$$

\n
$$
L_i = (i + \beta)[1 + g(R) \varphi(-1 + i + \beta + \upsilon_{\theta})]
$$

\n
$$
Q_i = (i - 1)[1 + g(R) \varphi(-2 + i + \upsilon_{\theta})]
$$
\n(26)

where $\varphi = ak_{\phi}/D_0$ represents the dimensionless flexibility coefficient. Using the Eq. (18), total number of *N* linear homogenous algebraic equations is generated. The non-trivial condition leads to set zero the determinant of coefficients matrix, as follows:

$$
|A - \lambda B| = 0 \tag{27}
$$

where A_{ij} and B_{ij} are determined as follows:

$$
A_{ij} = \int_{r_b}^{1} g(R) \left[\left(\frac{d^2 w_i}{dR^2} \right) \left(\frac{d^2 w_j}{dR^2} \right) + 2v_\theta \left(\frac{d^2 w_i}{dR^2} \right) \left(\frac{dw_j}{R dR} \right) + \beta^2 \left(\frac{dw_i}{R dR} \right) \left(\frac{dw_j}{R dR} \right) \right] R dR + \phi \left(\frac{dw_i}{dR} \right) \left(\frac{dw_j}{dR} \right)
$$
(28)

$$
B_{ij} = \frac{\lambda}{1 - r_b^{2\beta}} \left[R^{\beta - 1} - \frac{r_b^{2\beta}}{R^{\beta + 1}} \right] \int_{r_b}^{1} \left(\frac{\mathrm{d}w_i}{\mathrm{d}R} \right) \left(\frac{\mathrm{d}w_j}{\mathrm{d}R} \right) R \, \mathrm{d}R \tag{29}
$$

In the above equation, for the case of simply supported and clamped in outer edge, $\varphi=0$ and $\varphi=\infty$, respectively.

2.4 Buckling of circular solid plate

Regarding to Eq. (17), for circular solid plate $w_i(R)$ is defined as follows [9]

$$
w_i(R) = (a_i R^k + b_i R^{1+\beta} + 1)R^{2(i-1)}
$$
\n(30)

In order to obtain a_i and b_i as constants, the following boundary conditions must be satisfied:

2.4.1 Clamped outer edge, (C-F) plate

$$
b_i = \frac{k}{1 + \beta - k}, \qquad a_i = \frac{-1 - \beta}{1 + \beta - k} \tag{31}
$$

2.4.2 Simply supported outer edge, (S-F) plate

$$
a_i = \frac{(1+\beta)(-4+4i+\beta+\nu_\theta)}{(-1-\beta+k)(-4+4i+k+\beta+\nu_\theta)}
$$

$$
b_i = -\frac{k(-5+4i+k+\nu_\theta)}{(-1-\beta+k)(-4+4i+k+\beta+\nu_\theta)}
$$
(32)

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2.4.3 Elastically restrained against rotation

$$
a_i = -\frac{Q_i - L_i}{S_i - L_i}, \qquad b_i = -\frac{S_i - Q_i}{S_i - L_i}
$$
\n(33)

where

$$
S_i = (k + 2i - 2)[1 + g(R) K_{\varphi}(-3 + 2i + k + \nu_{\theta})]
$$

\n
$$
L_i = (2i + \beta - 1)[1 + g(R) K_{\varphi}(-2 + 2i + \beta + \nu_{\theta})]
$$

\n
$$
Q_i = 2(i - 1)[1 + g(R) K_{\varphi}(-3 + 2i + \nu_{\theta})]
$$
\n(34)

where A_{ij} and B_{ij} are determined as follows:

$$
A_{ij} = \int_0^1 g(R) \left[\left(\frac{d^2 w_i}{dR^2} \right) \left(\frac{d^2 w_j}{dR^2} \right) + 2v_\theta \left(\frac{d^2 w_i}{dR^2} \right) \left(\frac{dw_j}{R dR} \right) + \beta^2 \left(\frac{dw_i}{R dR} \right) \left(\frac{dw_j}{R dR} \right) \right] R dR + \varphi \left(\frac{dw_i(1)}{R dR} \right) \left(\frac{dw_j(1)}{R dR} \right)
$$
(35)

$$
B_{ij} = \lambda R^{\beta - 1} \int_0^1 \left(\frac{dw_i}{dR} \right) \left(\frac{dw_j}{dR} \right) R dR
$$

In the above equation, like before, for the case of simply supported $\varphi=0$ and clamped in outer edge $\varphi=\infty$.

3 NUMERICAL RESULTS

This section presents a number of numerical examples that shows the good performance of the proposed method, which was implemented in Mathematica 5.1 computer program. The results of the developed optimized Ritz method are compared with some other results which were obtained from FE method that are developed in ANSYS 10 commercial package. All calculation has been performed for $E_r=10000$ Mpa, $v_a=0.3$, $a=1$ m, $h_o=0.08$ m. It was revealed that convergent buckling load factor is obtained with 4-term series. Table (1) shows this convergence for centrally thicker annular orthotropic plate. In presenting results, the dimensionless buckling load factor is used. Value of this factor is obtained for plates of uniform and linearly continuously thickness.

3.1 Annular plate

Table 2 depicts the influence of parameters γ , β^2 , r_b on the buckling load factor. It is observed that with increasing the amount of β, buckling load factor is increased too. One observes that orthotropic plate (β >1) has more stiffness against buckling occasion in comparison to isotropic one. Furthermore, increasing parameter γ toward positive values makes the buckling load factor to increase. Regarding to Table 1, some values of r_b (r_b >1) decreases the buckling load factor *λ*, meanwhile some other values makes it decrease. As it was expected, shown in Table 3, clamped boundary condition represents the highest value of factor while the simply supported one shows the lowest. The influence of parameters γ , β^2 , r_b is the same as clamped case. Tables 4-6 depict the influence of rotational constant φ on buckling load factor for different value of β^2 . It is revealed that when $\varphi \to 0$, the boundary condition is closer to simply supported case and the loading factor shows lower than when $\varphi \rightarrow \infty$ the outer edge is clamped and stiff against rotation.

Table 1 Convergence study for annular orthotropic plate

Table 3 Buckling load factor variation with clamped outer edge

β ²	γ	r_b							
		0.1	0.2	0.3	0.4	0.5			
	-0.3	2.38864	2.08242	1.74291	1.45192	1.22152			
	-0.1	3.40413	2.99726	2.59067	2.25996	2.00307			
	$\mathbf{0}$	3.99418	3.53995	3.10666	2.76324	2.50023			
	0.1	4.64426	4.14536	3.69047	3.33985	3.007638			
	0.3	6.13934	5.56135	5.8046	4.7343	4.48982			
		3.865	3.70686	3.37779	2.95803	2.54578			
2	-0.3	5.91459	5.67527	5.2282	4.70576	4.21785			
	-0.1	7.14892	6.86634	6.36338	5.79828	5.28355			
	$\mathbf{0}$	8.53568	8.20873	7.65316	7.05245	6.51991			
	0.1	11.8043	11.3873	10.7398	10.0932	9.5504			
	0.3	7.44953	7.42653	7.29997	6.95221	6.35169			
		12.4039	12.3628	12.1571	11.6415	10.8251			
5	-0.3	15.5186	15.467	15.2169	14.6124	13.6953			
	-0.1	19.1024	19.0392	18.7421	18.0519	17.0371			
	$\overline{0}$	27.8088	27.7192	27.3225	26.4616	25.2822			
	0.1	12.7613	12.7592	12.7332	12.5904	12.1299			
	0.3	22.434	22.4299	22.3826	22.1401	21.4237			
		28.6802	28.6739	28.6134	28.3129	27.4558			
10	-0.3	35.9679	35.9621	35.889	35.5252	34.5213			
	-0.1	54.0108	54.0021	53.8957	53.3922	52.0821			
	$\mathbf{0}$	2.38864	2.08242	1.74291	1.45192	1.22152			
	0.1	3.40413	2.99726	2.59067	2.25996	2.00307			
	0.3	3.99418	3.53995	3.10666	2.76324	2.50023			

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Table 5 Load factor variation with edge elastically restrained $(\beta = \sqrt{2})$

3.2 Circular solid plate

Figs. 2 and 3 illustrate the variation of bucking load factor with respect to boundary condition case, orthotropic and geometry parameters β^2 and γ . As shown, plate with γ <0 (centrally thicker solid plate, h_a/h_o <1) has lower buckling load factor than plate with γ >0 (centrally thinner circular plate, *h_a*/*h_o*>1). Buckling factor pattern for all boundary conditions are similar.

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Variation of buckling load factor with respect to orthotropic parameter and non-dimensional geometric parameter with clamped outer edge.

F Fig. 3

Variation of buckling load factor with respect to orthotropic parameter and non-dimensional geometric parameter with simply supported outer edge.

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Fig. 4 Variation of buckling load factor with respect to orthotropic parameter for different boundary conditions.

Table 7 Comparison of results for buckling load factor in Optimized Ritz method (I) and ANSYS (I .
II)

β^2									
		-0.3	-0.2	-0.1		0.1	0.2	0.3	
		8.05	10.03	12.24	14.68	17.36	20.28	23.43	
	\mathbf{I}	7.8	9.825	12.11	14.68	17.53	20.69	24.15	
1.4		9.87	12.43	15.32	18.54	22.1	26.04	30.26	
	П	9.72	12.31	15.24	18.54	22.21	26.28	30.75	
1.8		11.56	14.69	18.25	22.24	26.67	31.57	36.94	
	П	11.55	14.67	18.23	22.23	26.7	31.66	37.11	

Fig 4 illustrates the influence of rotational constant φ on buckling load factor for different values of β^2 . For different boundary conditions, the obtained result is the same as the annular plate. In fact, for simply supported outer edge, the evaluated buckling load factor is lower than clamped and elastically restrained against rotation in outer edge. As shown in Table 7, the results obtained from present method compare very well with obtained from ANSYS commercial package. This confirms the accuracy of Optimized Ritz method in buckling analyzing of circular plates.

4 CONC CLUSIONS

The buckling analysis of orthotropic circular annular and solid plates under uniform radial compression loading with uniform and linearly varying thickness was presented. The inner edge is free while the outer edge is under different types of classical boundary conditions and also with edges elastically restrained against rotation. This is implemented by optimized Ritz method. In this method, an optimization exponential parameter is utilized that buckling load factor was minimized with respect to it. Following are some of the concluding remarks:

- I. Increasing orthotropic parameter and radius ratio (inner to outer radius), increases the resistance of plate against buckling phenomena.
- II. Plate with clamped boundary condition exhibits the higher value of the buckling parameter, while the simply supported case shows lowest. Also, plate with edges elastically restrained against rotation has value of between two boundary condition cases.
- III. Centrally thinner circular plate has higher buckling parameter than centrally thicker one.

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