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(L/D)

Archive of SID

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LVDT

(Oven)

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[] ASTM

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[] (ISRM)

L/D

L/D

(L/D)

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$$E_d = \rho V_s^2 \frac{(3V_p^2 - 4V_s^2)}{(V_p^2 - V_s^2)}$$

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(L/D)

$$G_d = \rho V_s^2$$

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$$v_d = \frac{(V_p^2 - 2V_s^2)}{2(V_p^2 - V_s^2)}$$

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v_d G_d E_d

ρ V_s V_p

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L/D

OYO

Sonic-Viewer-SX

L/D ()
(m/s)

R

L/D

$$V_s = \left(\frac{L}{D} \right) + (R = \dots)$$

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$$V_s = \left(\frac{L}{D} \right) + \dots (R = \dots)$$

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$$V_s = \left(\frac{L}{D} \right) + \dots (R = \dots)$$

(V_s)

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$$V_s = \left(\frac{L}{D} \right) + \dots (R = \dots)$$

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L/D

L/D

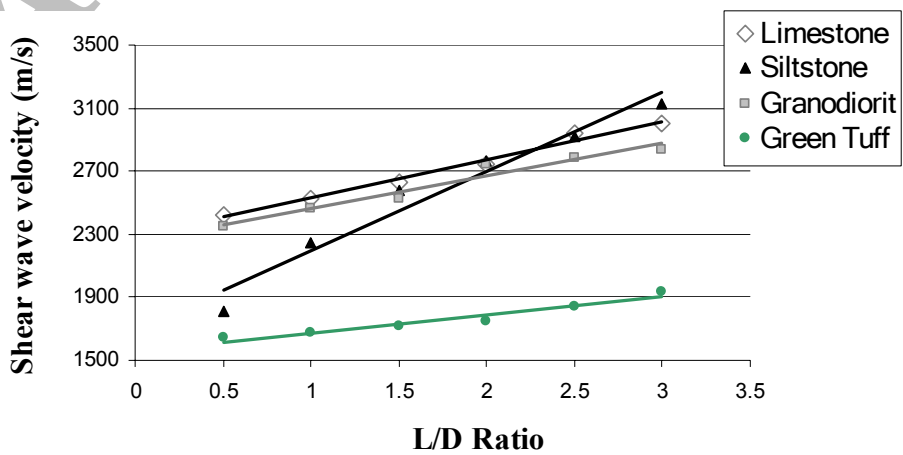
		(gr/cm ²)	(gr/cm ²)		
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L/D

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	(GPa)	(GPa)	(m/s)	(m/s)		(GPa)	(GPa)	(m/s)	(m/s)	
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	(GPa)	(GPa)	(m/s)	(m/s)		(GPa)	(GPa)	(m/s)	(m/s)	
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(m/s)

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$$G_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots) \quad (E_d)$$

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$$G_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots) \quad L/D$$

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(v_d)

L/D

L/D

(GPa)

()

$$\frac{1}{D} \quad L/D$$

$$E_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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$$E_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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L/D

$$E_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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$$E_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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$$v_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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(G_d)

$$v_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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L/D

$$v_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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()

L/D

$$v_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

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L/D

(GPa)

()

(V_p)

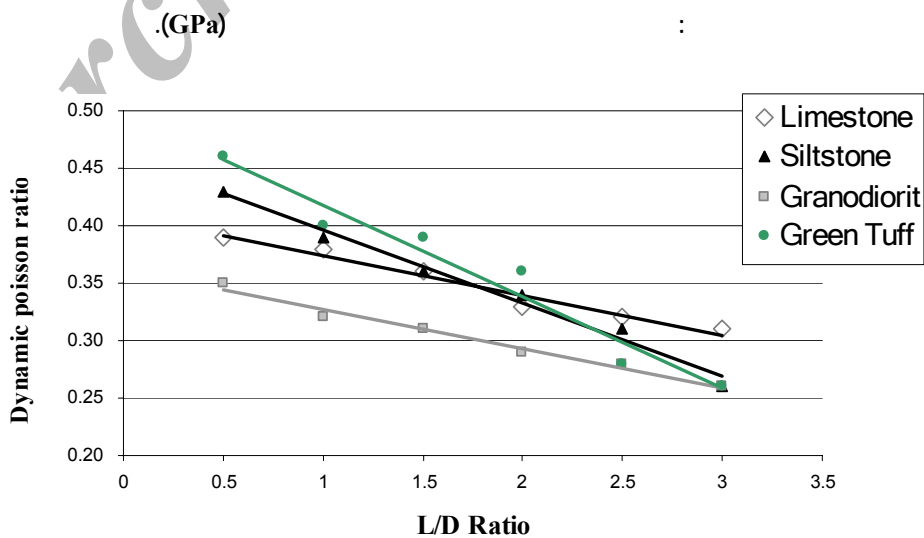
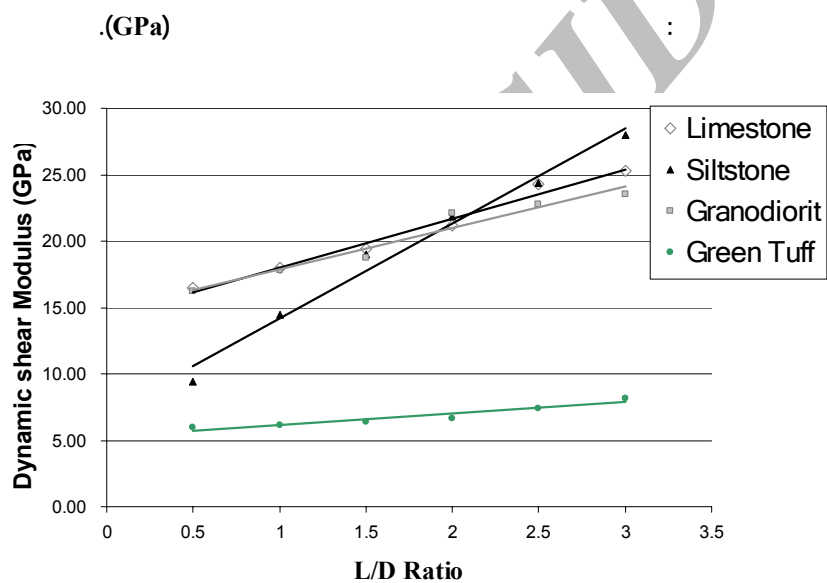
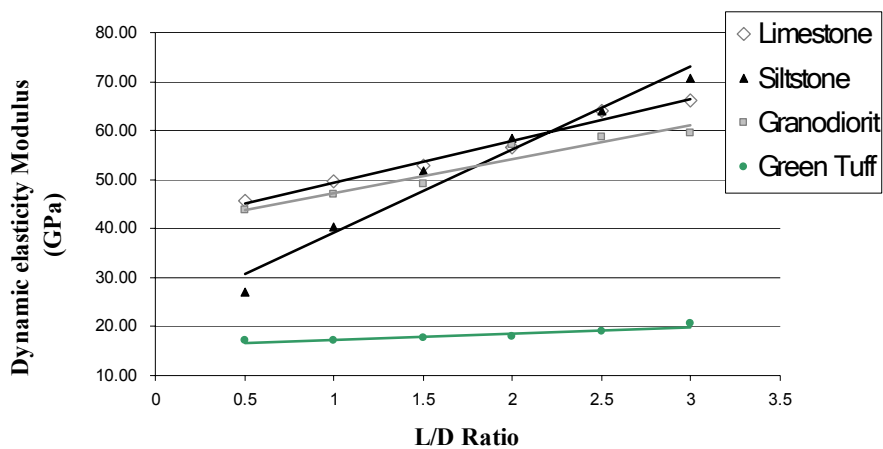
$$G_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

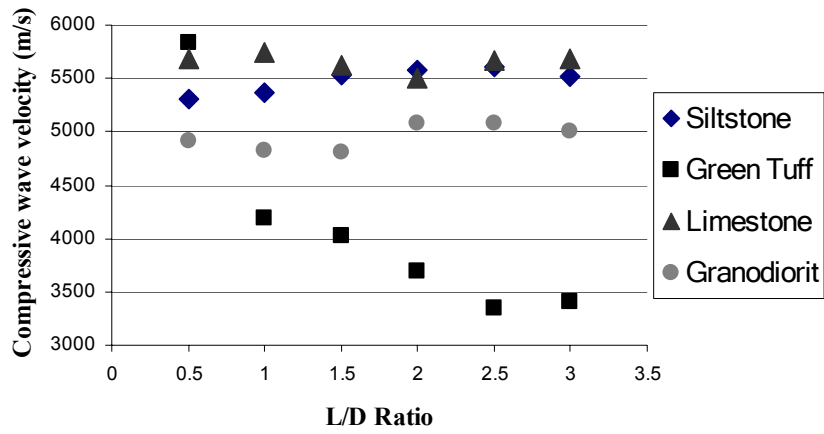
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$$L/D$$

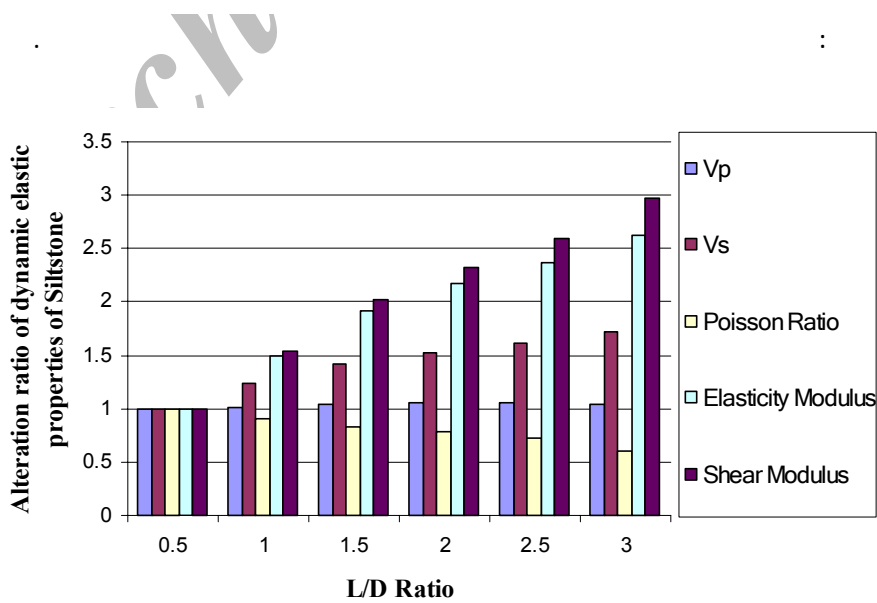
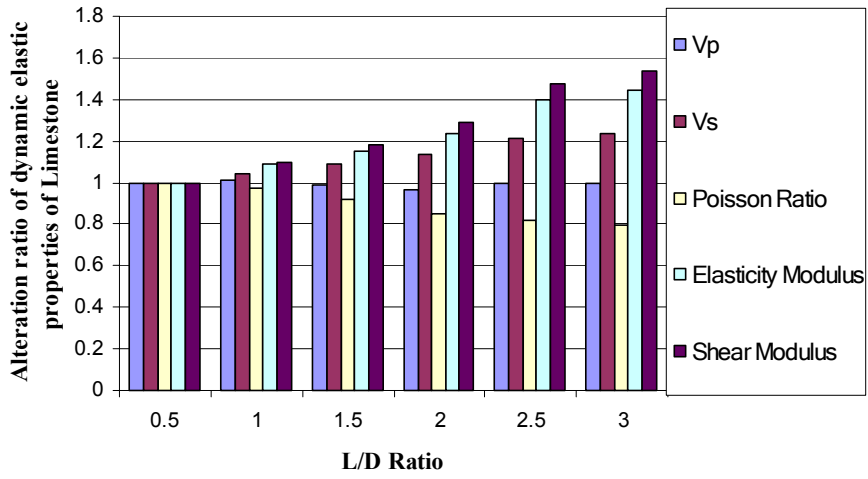
$$G_d = \frac{1}{D} \left(\frac{L}{D} + 1 \right) \quad (R = \dots)$$

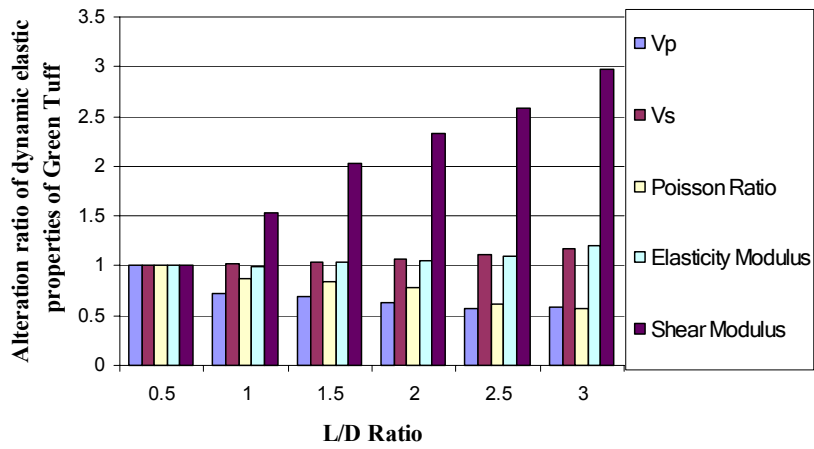
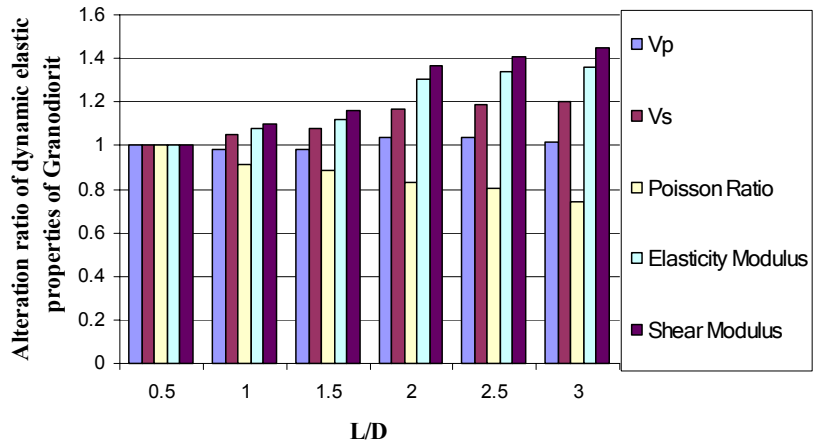
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(m/s)





Archiv

ISRM ASTM

L/D

L/D

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ASTM

Vs

L/D

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- 1 - Linear Variable Differential Transformer
- 2 - Strain Gauge
- 3 - Transducers