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## **Analysis of Inflows to Multiobjective Reservoir in Chance Constrained Goal Programming Model (A Case Study of Mahabad Reservoir)**

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### **Abstract**

In order to investigate behavior of stochastic inflows to multiobjective reservoir a probabilistic model has been used .This model can describe river flow for the purpose of forecasting future situations. To convert chance constrained goal programming (CCGP) model to its deterministic equivalents model, OSM computer software has been developed which is written in FORTRAN 77. OSM software can extract conditional and nonconditional cumulative distribution function (CDF) of inflows to reservoir and calculates inverse CDF of inflows for flood and drought control reliability by using Newton's differential interpolation method. The model is applied to the Mahabad multiobjective reservoir which is a portion of the Urmia lake watershed . This reservoir is constructed to control water for several purposes such as municipal water supply, irrigation demands, flood control and hydroelectric power generation. Use of this model allows the reservoir manager to rank various goals according to their relative importance.

**Key words:** Optimization, Stochastic inflows, Multiobjective, Reservoir operation, Wet and dry periods.

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\* Chance Constrained Goal Programming (CCGP)

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3- Loucks

4-Delaware

5-Mures

6-Simonovic &amp; Marino

7-Reliability Programming

8-Changchit &amp; Terrel

9- Srinivasan &amp; Simonovic

10- Manitoba

11- Dandy et all

12- Canberra

13- Full Optimization

14- Simplified Optimization

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1-Run off

2- Chance Constrained

$$\alpha_t = P : \\ (S_{\max_t})^t \quad S_t - t \\ . \quad t \\ (S_{\max_t}) \\ (FC)$$

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$$S_{\max_t} = S_{\max} - FC_t \quad ( )$$

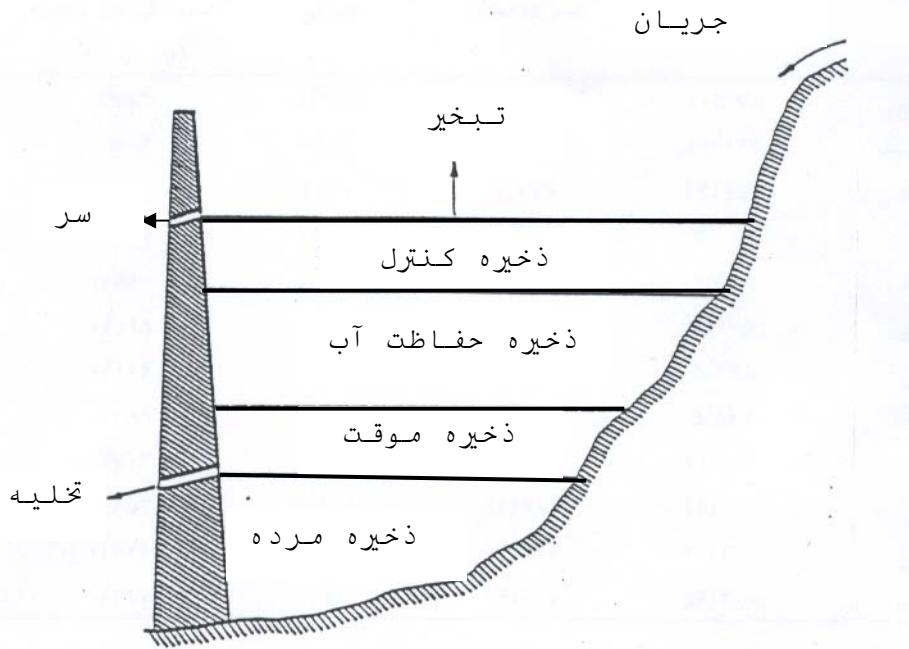
$$S_t = S_{t-1} + I_t - W_t - R_t - G_t - EV_t \quad ( )$$

$$I : \\ ) \quad W( \\ G( \quad ) \quad R( \\ EV( \quad ) \quad ) \quad ( ) \quad [ ] \\ . \quad ( \quad ) \quad ( ) \quad ( ) \quad ( ) \\ [ ] \quad ( ) \quad ( ) \quad ( ) \quad ( ) \\ EV_t = A_t \left[ \frac{e_t + P_t}{1000} \right] \quad ( ) \\ t \quad e_t : \\ ) t \quad P_t ( \quad ) \quad : \\ . \quad ( \quad ) t \quad A_t ( \quad ) \quad : \\ : \quad A_t \quad P(S_t \leq S_{\max_t}) \geq \alpha_t \quad ( )$$

$$A_t = \theta + \Psi \left[ \frac{S_t + S_{t-1}}{2} \right] \quad ( )$$

$\Psi \quad \theta :$

- 
- 1- Dead storage
  - 2- Buffer storage
  - 3- Conservation storage
  - 4- Flood control storage



$$\begin{aligned}
 & n_{i,t} \quad P_{i,t} \quad S_t \quad (\ ) \\
 t & i \quad : \quad (\ ) \\
 & P(S_t \geq S_{\min_t}) \geq \beta_t \quad (\ ) \\
 & P(S_{\max_t} - S_{t-1} + W_t + R_t + G_t + EV_t \geq F_{I_t}^{-1}(\alpha_t)) \quad (\ ) \\
 & \beta_t \quad t \quad S_{\min_t} \quad S_{\max_t} - S_{t-1} + W_t + R_t + G_t + EV_t \geq F_{I_t}^{-1}(\alpha_t) \quad (\ ) \\
 & (\ ) \quad (\ ) \quad (\ ) \quad (\ ) \\
 & [ ] \quad (\ ) \quad (\ ) \quad (\ )
 \end{aligned}$$

$$F_{I_t}^{-1}(\alpha_t) + S_{t-1} - R_t - W_t - G_t - EV_t - P_{i,t} + n_{i,t} = S_{\max_t} \quad (\ )$$

1- Cumulative Distribution Function (CDF)

$$F(y|x) = \begin{cases} B & Z_c < 0 \\ 1-B & Z_c \geq 0 \end{cases} \quad (1)$$

$$B = 0.5 \left[ 1 + 0.196854 (|Z_c|) + 0.115194 (|Z_c|^2) \right]^{-4} + 0.000344 (|Z_c|^3) + 0.019527 (|Z_c|^4) \quad (2)$$

CDF

$$\mu(y|x) = \mu_y + \rho \frac{\sigma_y}{\sigma_x} (x - \mu) \quad (3)$$

$$\text{Var}(y|x) = \sigma_c^2 = \sigma_y^2 (1 - \rho^2) \quad (4)$$

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Minimize  $Z = P_1 \sum_{t=1}^T n_{1,t} + P_2 \sum_{t=1}^T n_{2,t} + P_3 \sum_{t=1}^T n_{3,t} + P_4 \sum_{t=1}^T n_{4,t}$  (5)

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$$IR_{\min} \leq IR_t \leq IR_{\max} \quad ( )$$

MTAR

PTAR

PTAR

$$W_{\max}$$

$$IR_{\max} \quad IR_{\min}$$

$$S_{\max} \quad S_{\min}$$

$$h_t \cdot \begin{matrix} & \\ & \beta \quad \alpha \quad t \end{matrix} \quad W_t - P_{1,t} + n_{1,t} = MTAR_t \quad ( )$$

$$D_t - G_t - R_t - IR_t - W_t \quad IR_t - P_{2,t} + n_{2,t} = IRTAR_t \quad ( )$$

$$\xi_t \cdot \begin{matrix} & \\ & t \\ t & \end{matrix} \quad t \quad P_{\max_t}$$

$$R_t \cdot \xi_t - P_{3,t} + n_{3,t} = PTAR_t \quad ( )$$

$$F^{-1}(\alpha_t) + S_{t-1} - R_t - W_t - G_t - EV_t - P_{4,t} + n_{4,t} = S_{\max_t} \quad ( )$$

$$\xi_t = a + bS_{t-1} \quad ( )$$

$$P_{\max_t} = c + dS_{t-1} \quad ( )$$

$$\xi_t \cdot \begin{matrix} & ( ) & ( ) \\ & ( ) & ( ) \end{matrix} \quad \begin{matrix} d & c & b & a \\ \cdot & & & \end{matrix} \quad P_{\max_t}$$

$$S_{\min} \leq S_t \leq S_{\max} \quad ( )$$

$$R_t \cdot \xi_t \leq h_t \cdot P_{\max_t} \quad ( )$$

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$$R_t + G_t = D_t \quad ( )$$

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$$IR_t \leq D_t \quad ( )$$

$$W_t \leq W_{\max} \quad ( )$$

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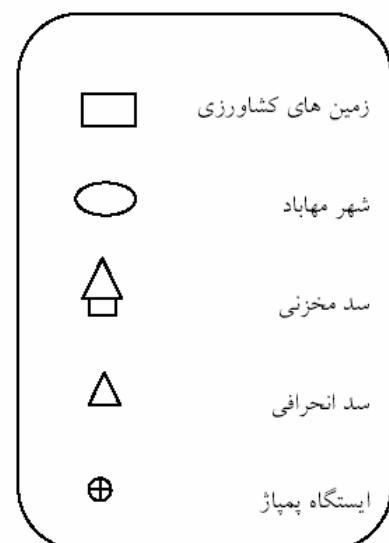
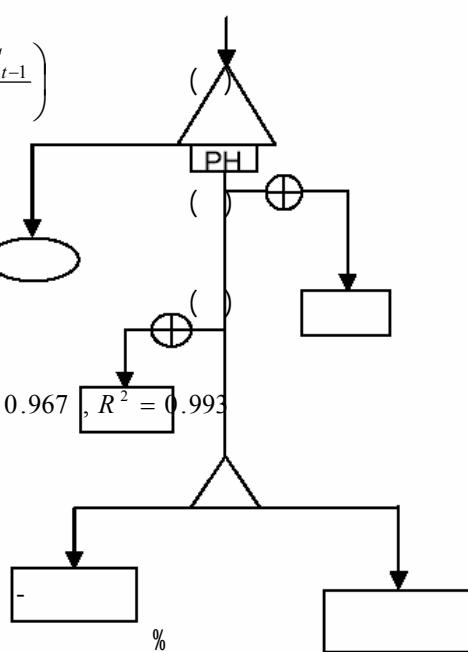
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$$A_t = 3.303 + 0.038 \left( \frac{S_t + S_{t-1}}{2} \right)$$

$$\xi_t = 28.926 + 0.3964 S_{t-1}$$

$$P_{\max_t} = 2.66 + 0.026 S_{t-1}$$

$$R^2 = 0.984 \quad R^2 = 0.967 \quad R^2 = 0.993$$



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CDF( )

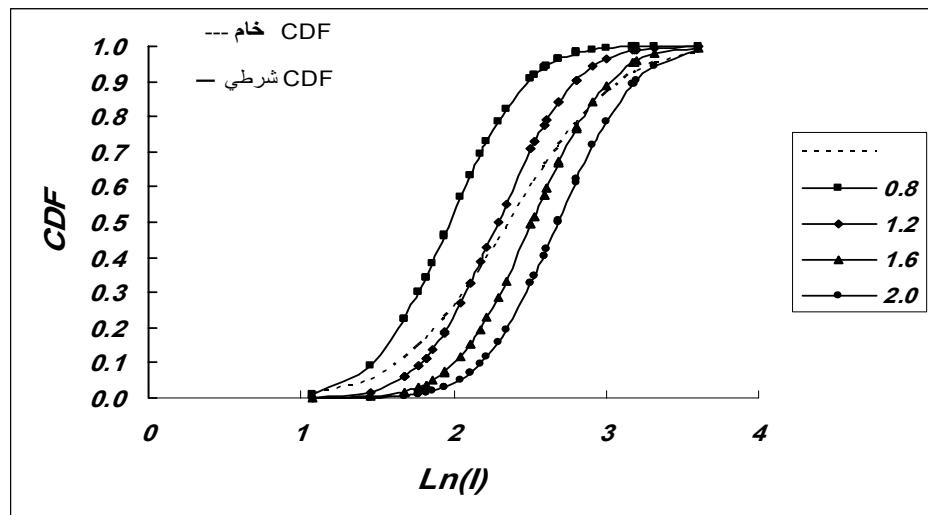
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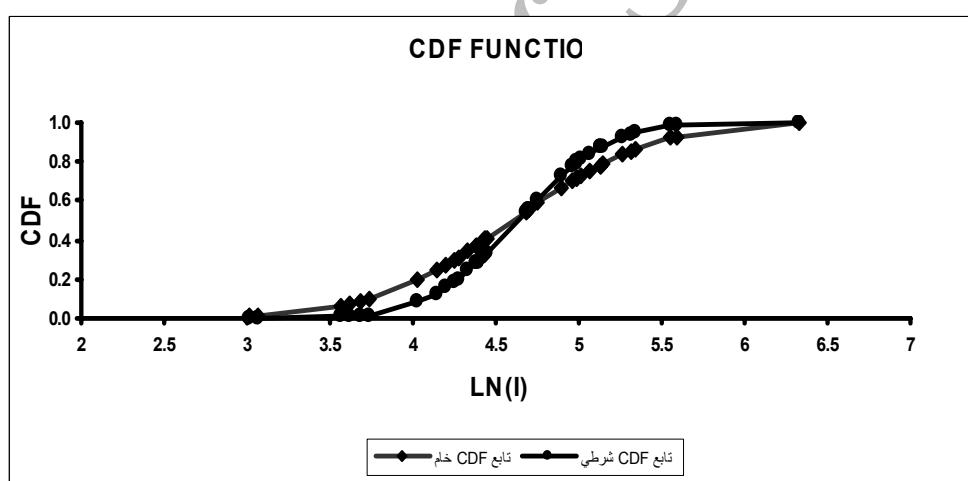
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CDF

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 $(F_{I_t^{-1}}(\alpha))$ 

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 $F_{I_t^{-1}}(\alpha)$ 

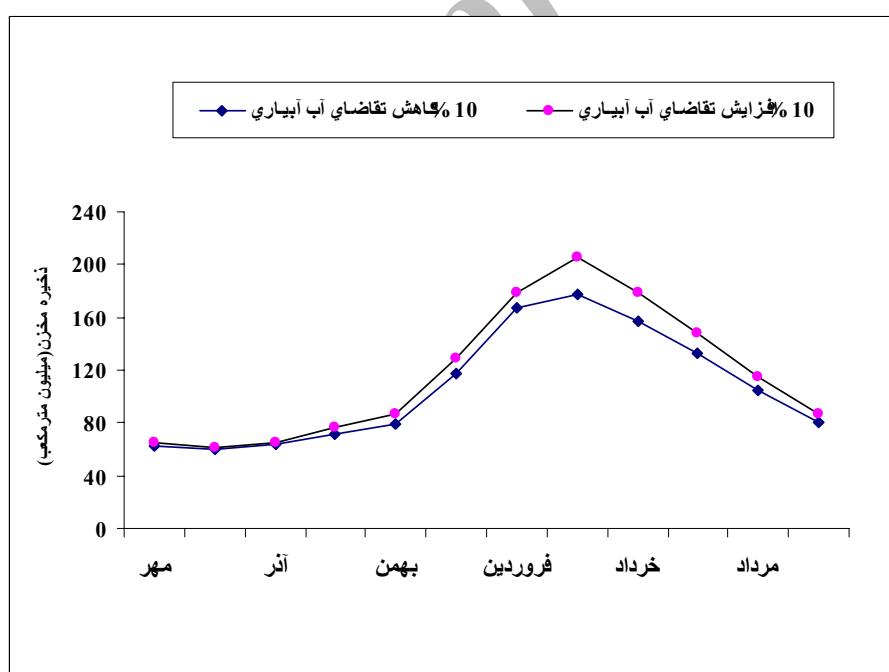
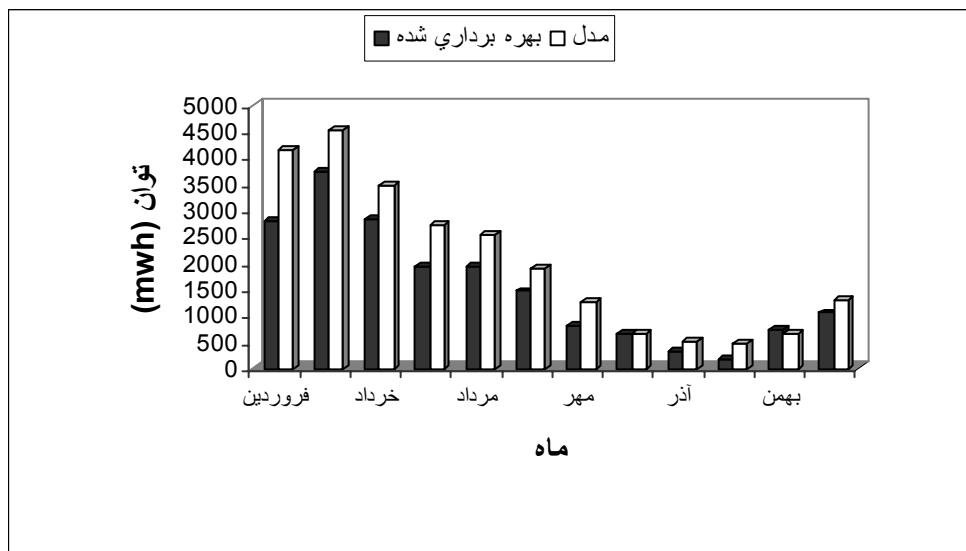
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